

A Step-by-Step Guide to Measure Cosmological Parameters from DES SNIa

Dan Scolnic





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What we know about SNIa:

- Carbon-Oxygen white dwarf accretes matter from companion, reaches near Chandrasekhar limit, explodes

- Type Ia SNe luminosities can be standardized to $\sim 10\%$ by correct brightness for decline-rate and color

- 1 SN per galaxy per century

- Enough to make pretty movies..



www.eso.org

What we know about SNIa:

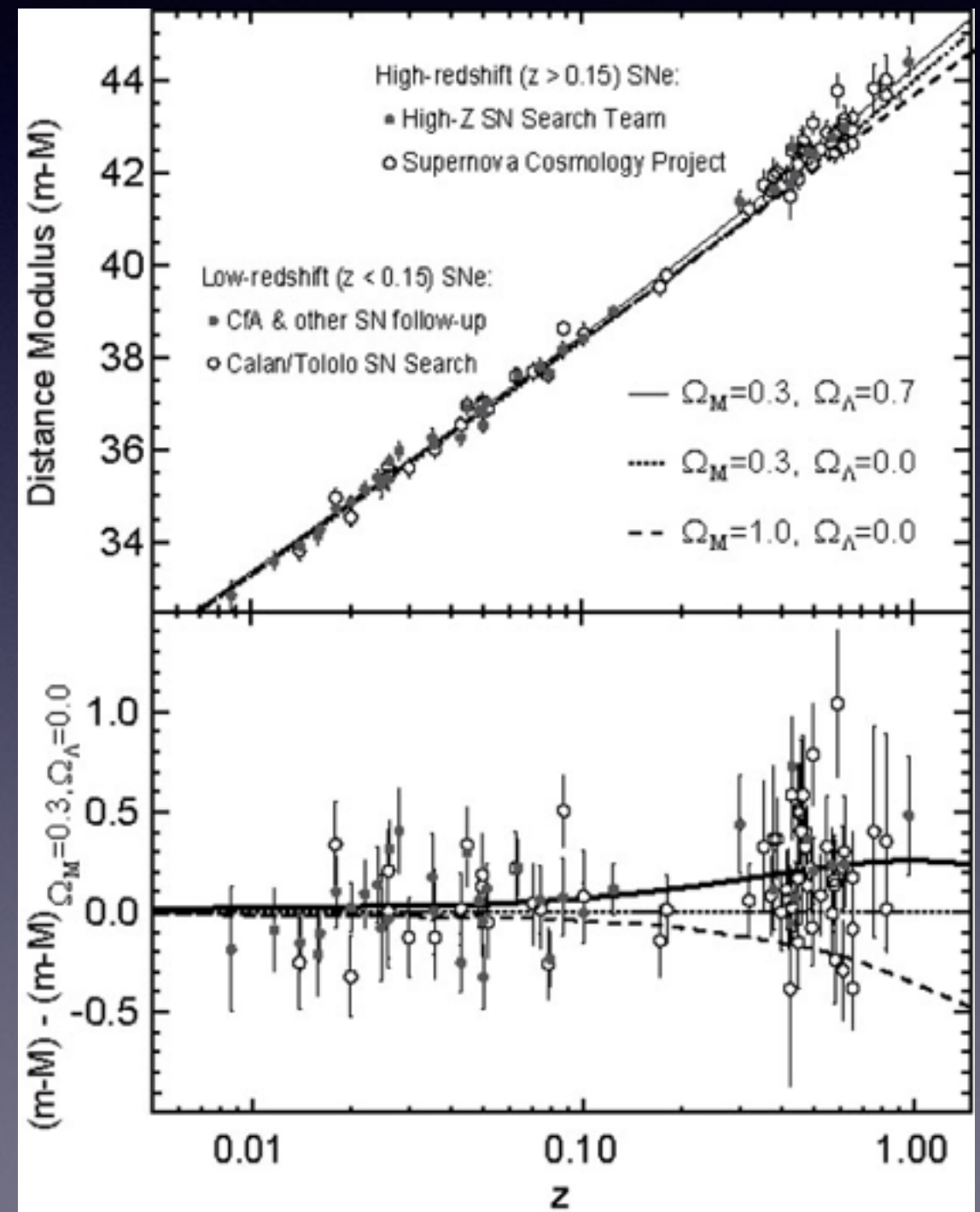
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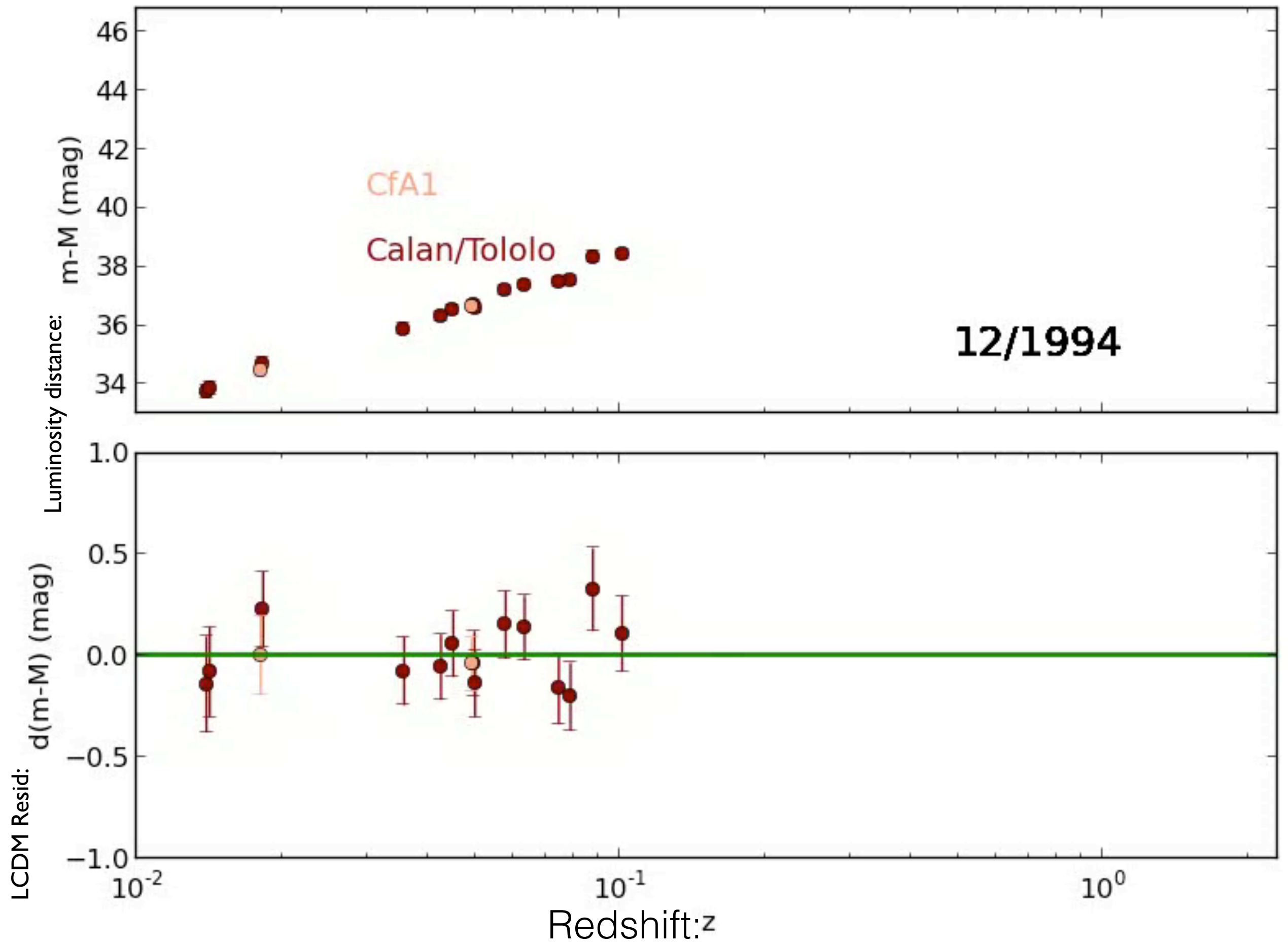
What we don't know about SNIa:

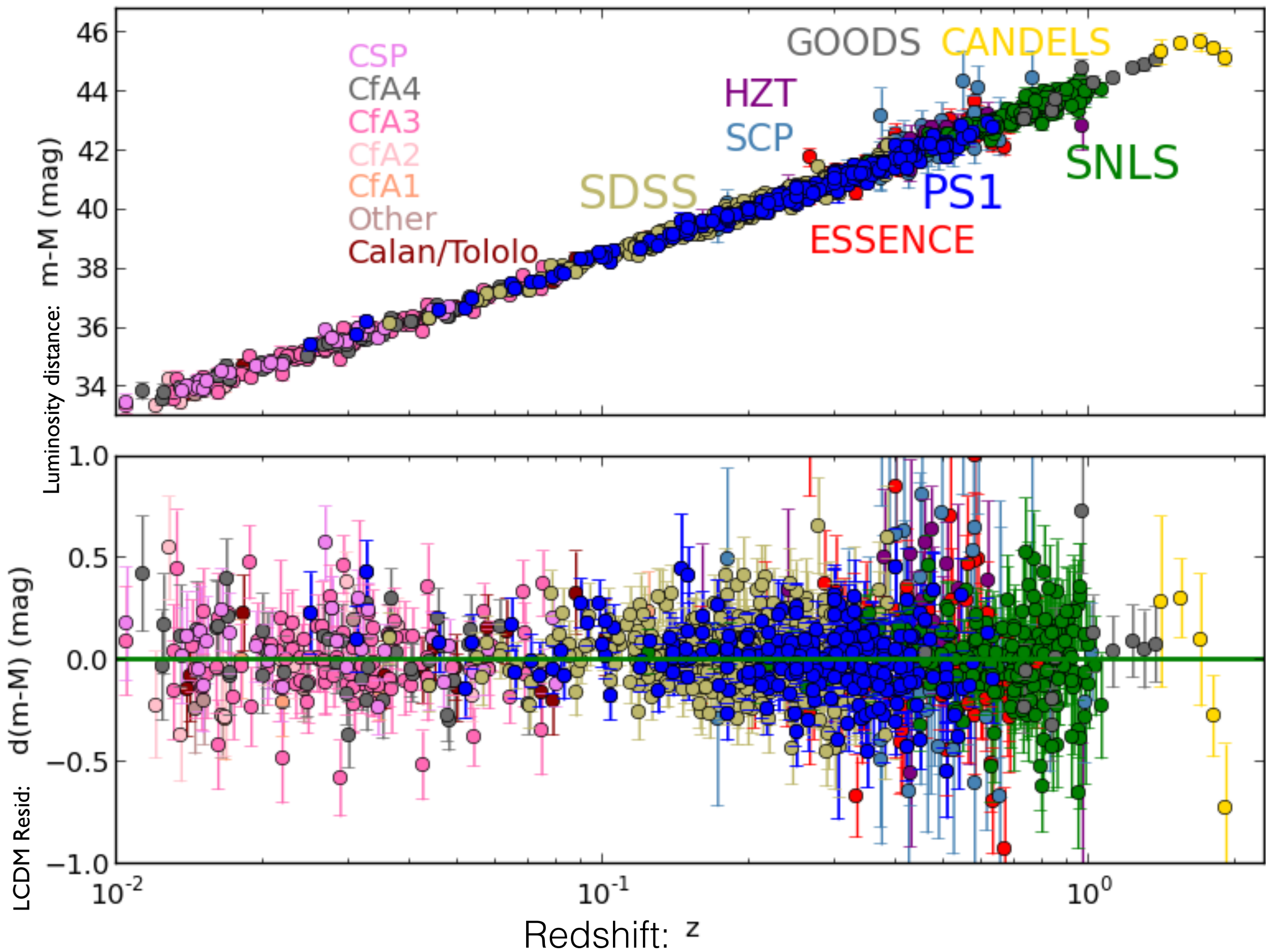
- What is companion star to white dwarf (double degenerate or single degenerate)?
- What's the remaining 10% due to?
- Why is there a correlation between galaxy type and luminosity?

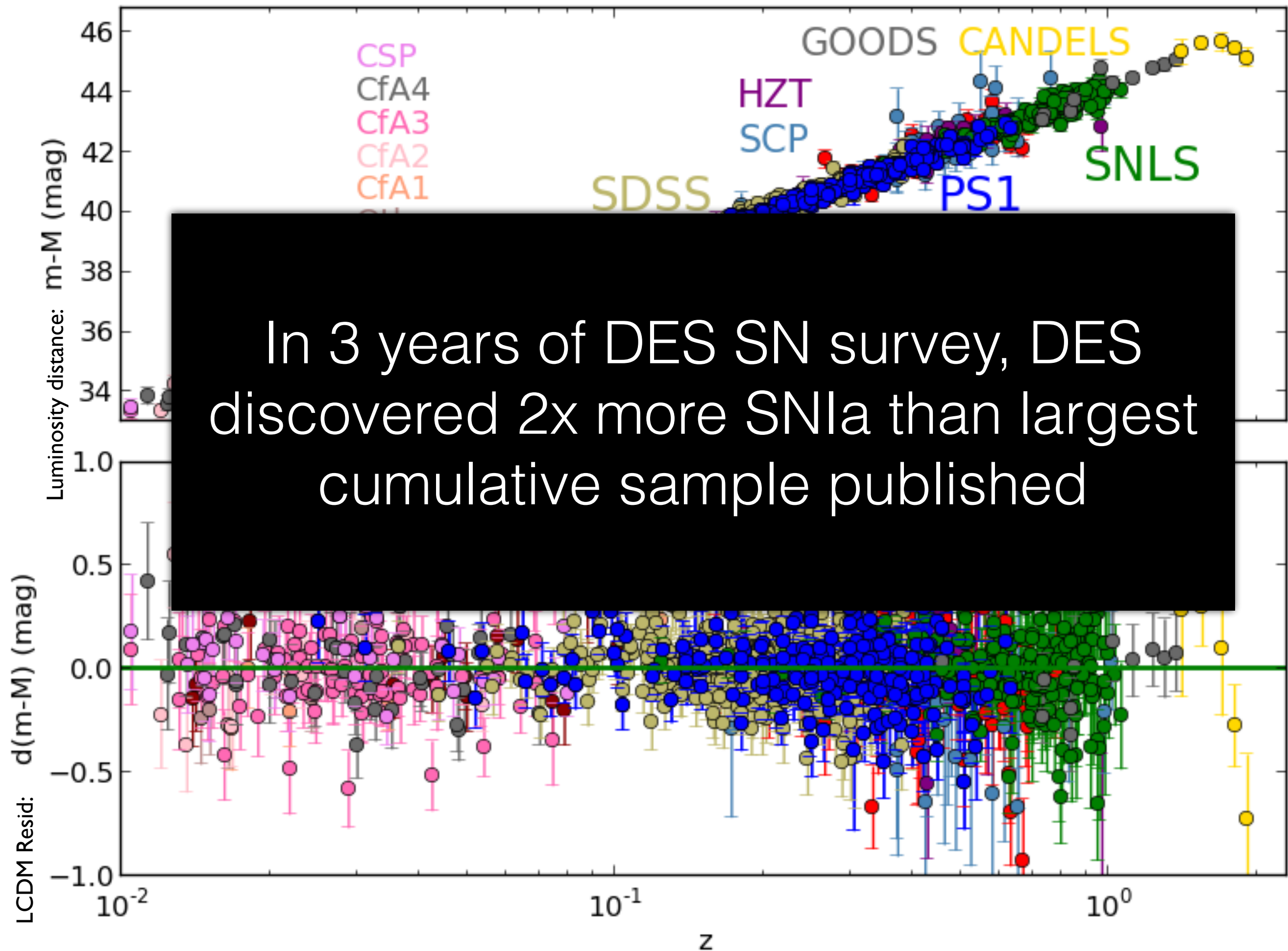
How measurements of SNIa are used

- SNIa intrinsic luminosity is known (to 10%) and apparent luminosity can be measured
- Ratio of two provides the luminosity-distance (d_L) of the supernova
- Redshift measured independently from spectroscopy
- Each SNIa can be used for a single d_L (z) on a Hubble diagram





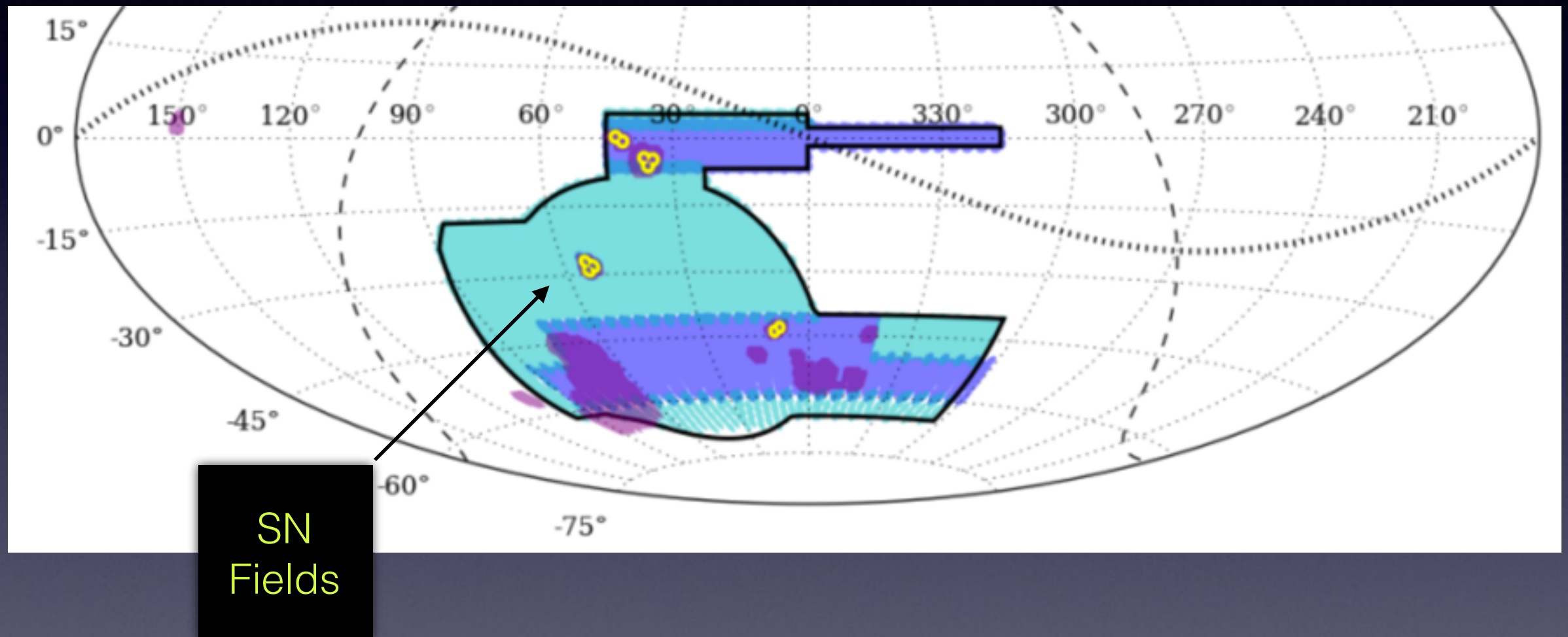




This is the past/current/future status of SNIa surveys

	Past/Current	Current/Future	More Future
Low-z: $z < 0.1$	CfA I-4, SNF, CSP	CSP, PTF, Foundation	LSST?
Mid-z: $0.1 < z < 1.0$	SDSS, SNLS, ESSENCE	PS I, DES	LSST
High-z: $1.0 < z$	HST	HST-CANDELS/ Frontier	Euclid/ WFIRST
#s:	~1000	~10,000	>100,000

The basics of the DES SN survey

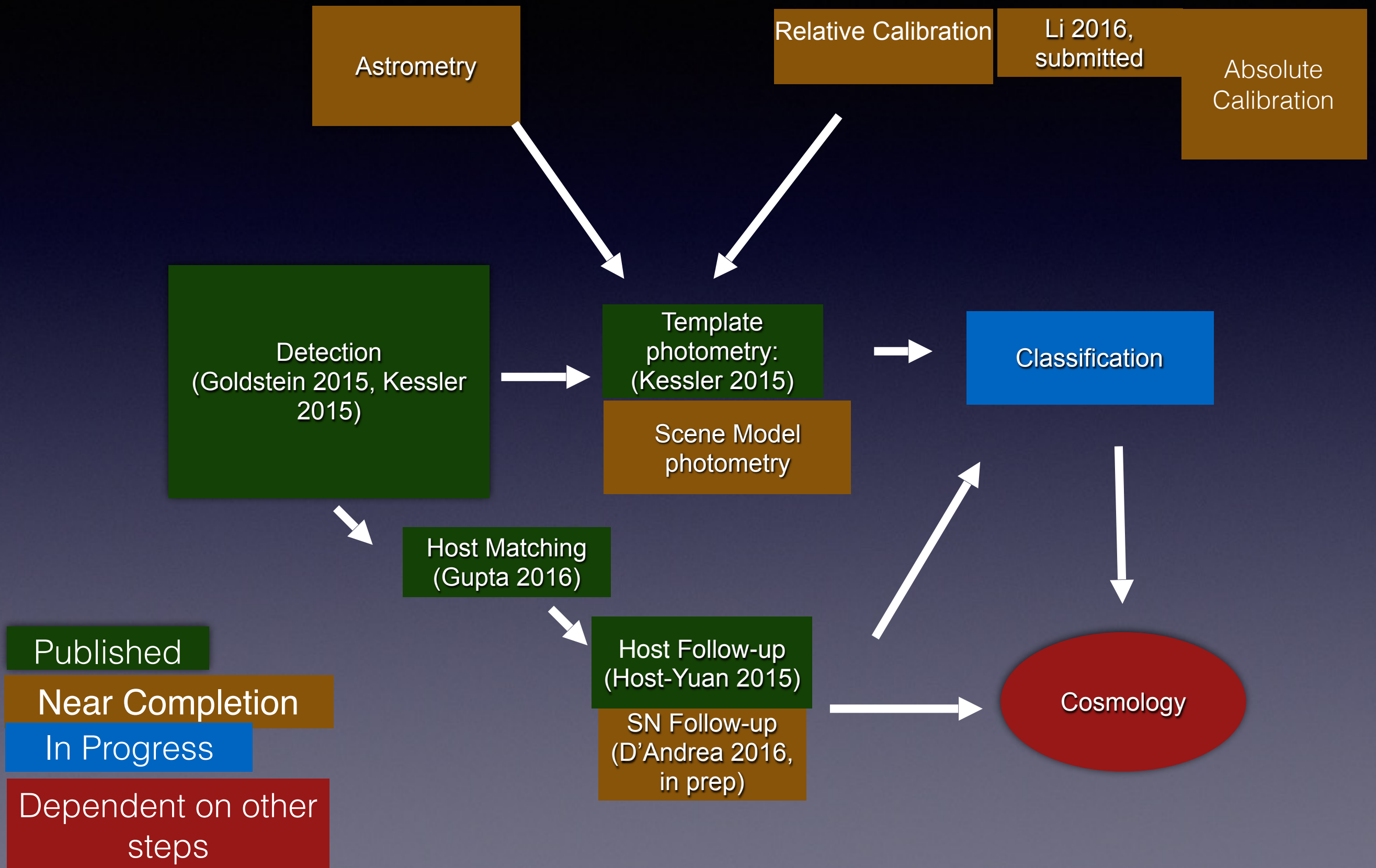


- 5 observing seasons of 5 months, ~ 7 day cadence.
- 3 sq. degree FOV, 2.7 sq. degree active
- 8 shallow fields ($r \sim 23.5$ mag)
2 deep fields ($r \sim 24.5$ mag)
- Red sensitive CCDs to probe higher redshifts
- OzDES follow-up with AAT for host galaxy redshifts
- SN fields overlap with existing deep imaging

SN Analysis Basics

- Discovery
- Follow-up
- Photometry
- Calibration
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- Systematics
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- Cosmology

Roadmap to Cosmology

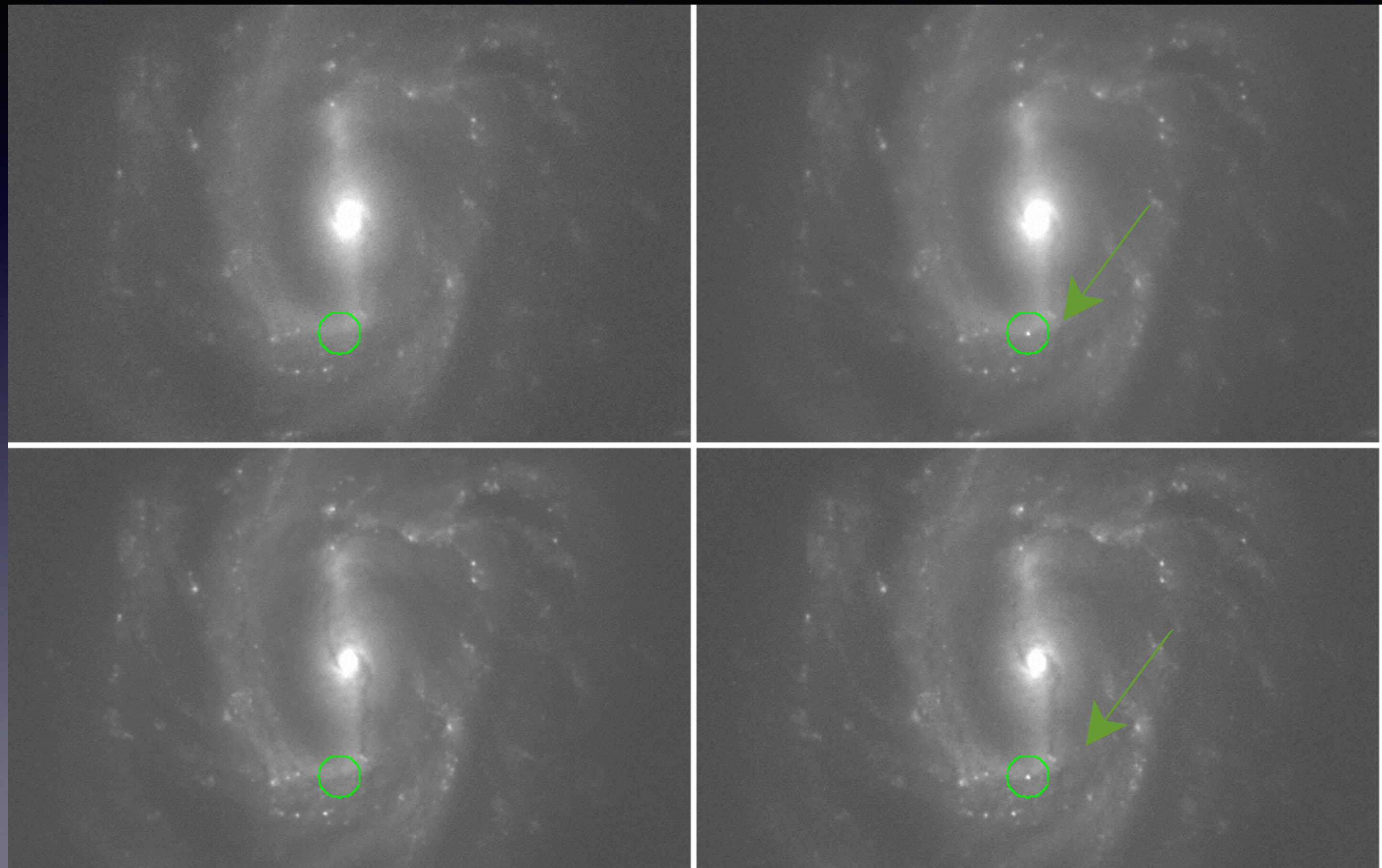


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DES is considered a rolling survey that with repeated observations and high depth, finds hundreds of SN a year

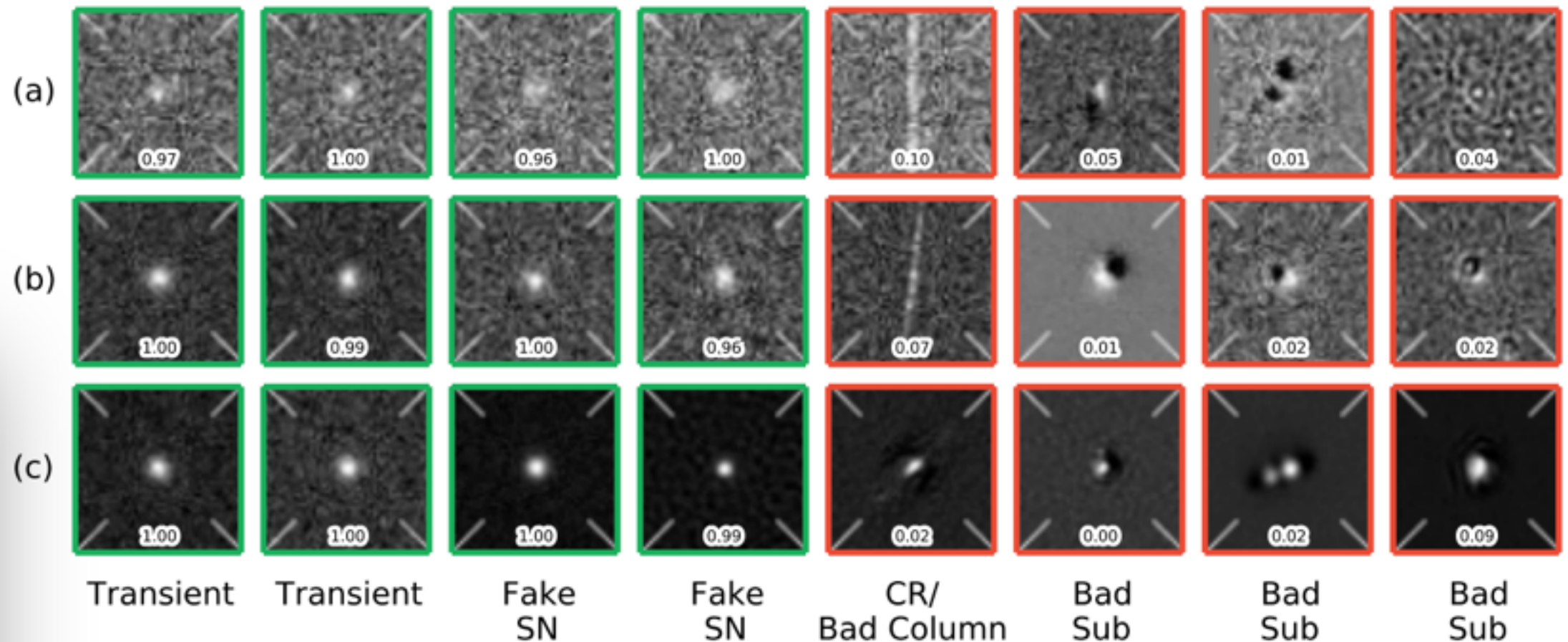
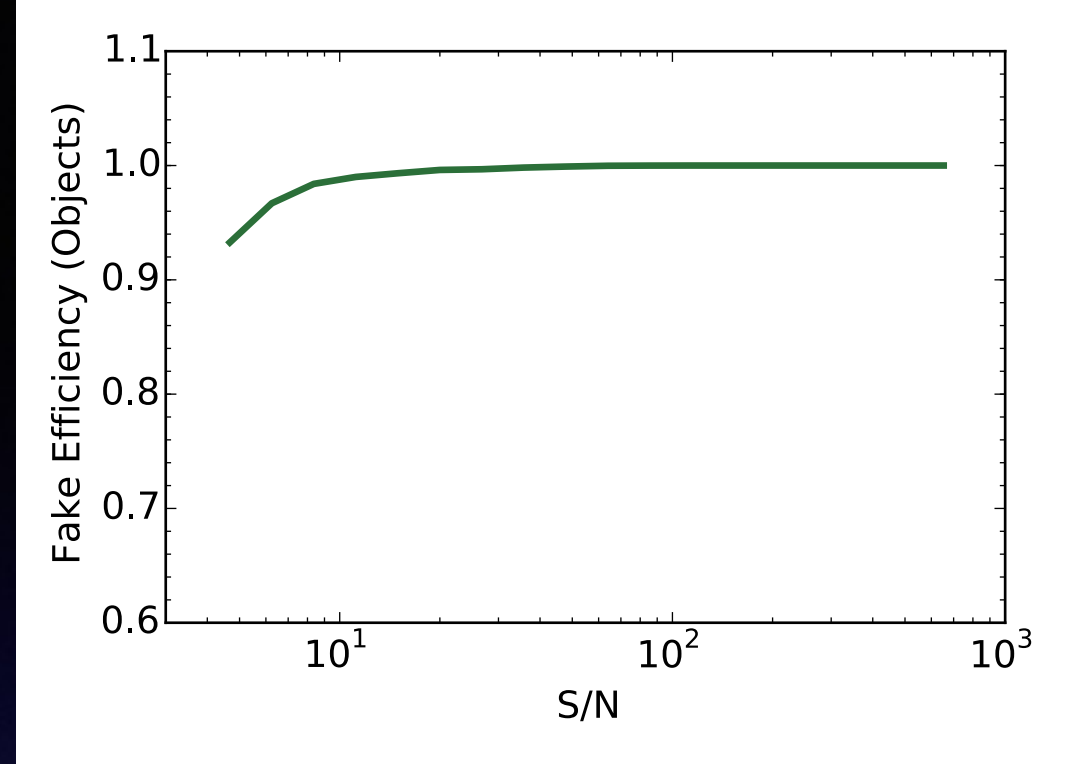
Supernovae are found by subtracting observations separated by time



Automated Scanning

(Goldstein et al 2015)

- Removes factor of 13 of junk, only 1% lost
- Efficiency monitored with extensive 'fake' pipeline



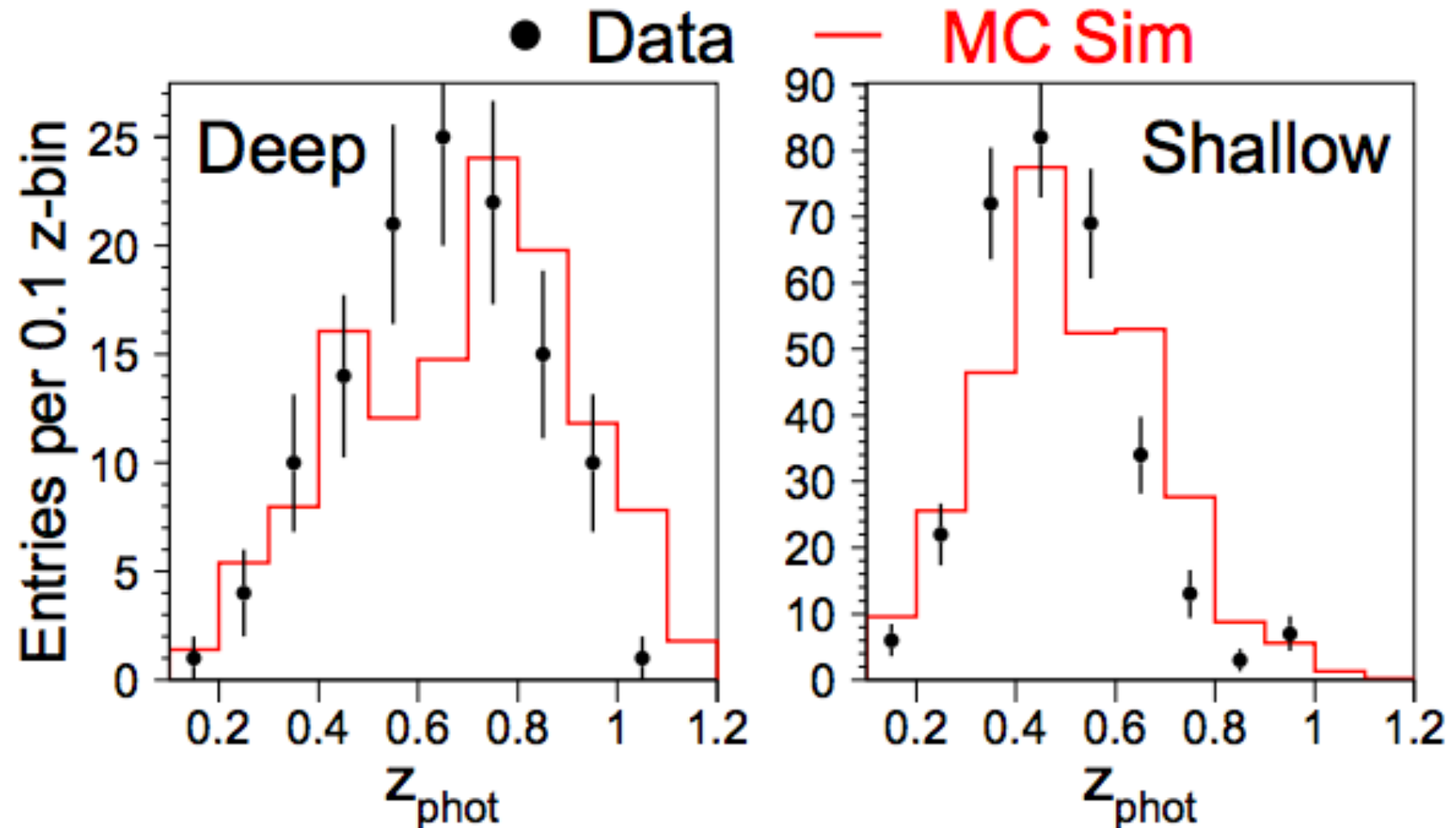
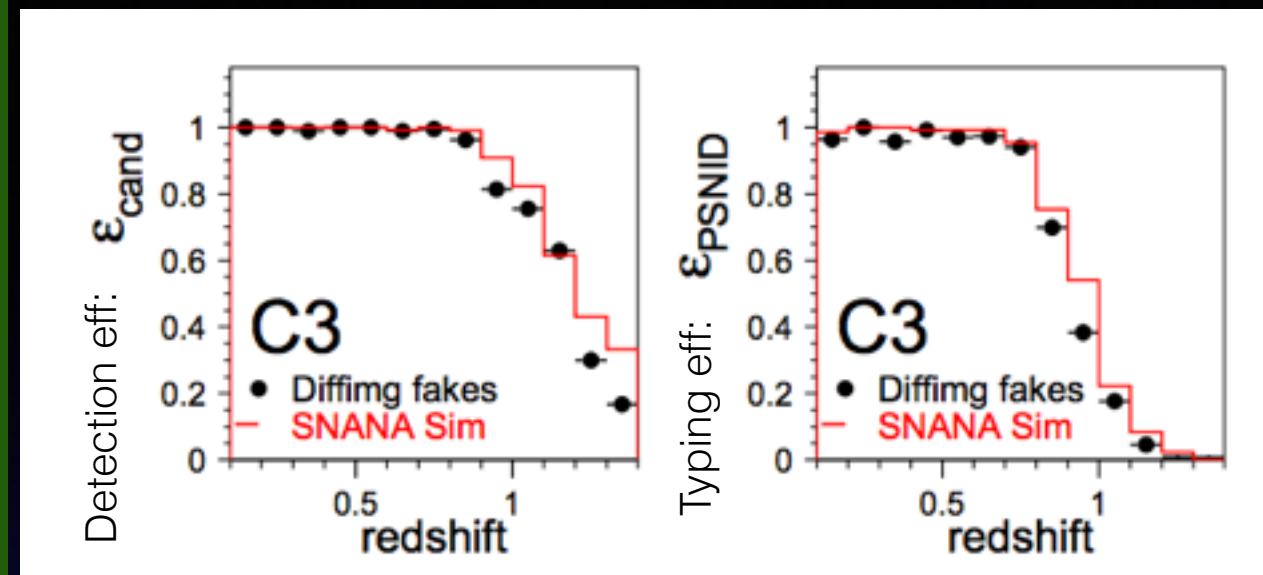
Difference Imaging Pipeline

(Kessler et al 2015)

-Injects full fake light curves through entire discovery/photometry pipeline

-Simulations are excellent match to data

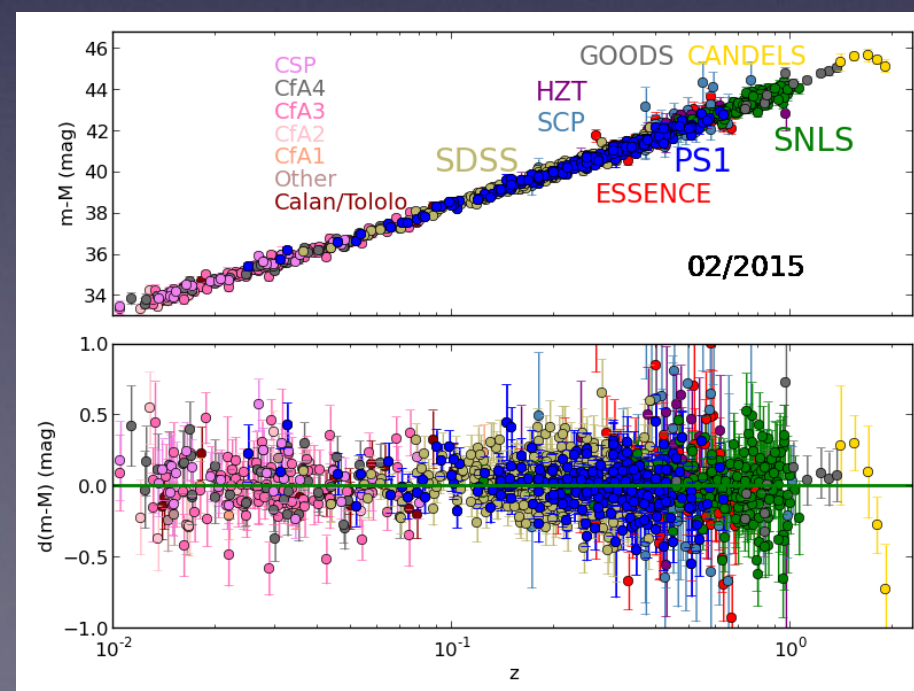
-Can trace all the way to distance measurements, cosmology biases



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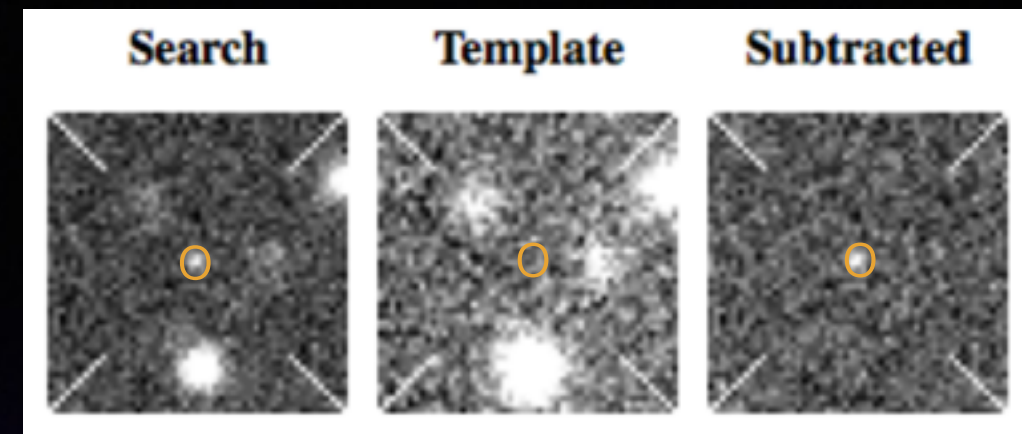
For DES, follow-up is necessarily primarily to get a redshift for the SN. The light curve gives a distance (y-axis on Hubble diagram), the redshift is the x-axis point.



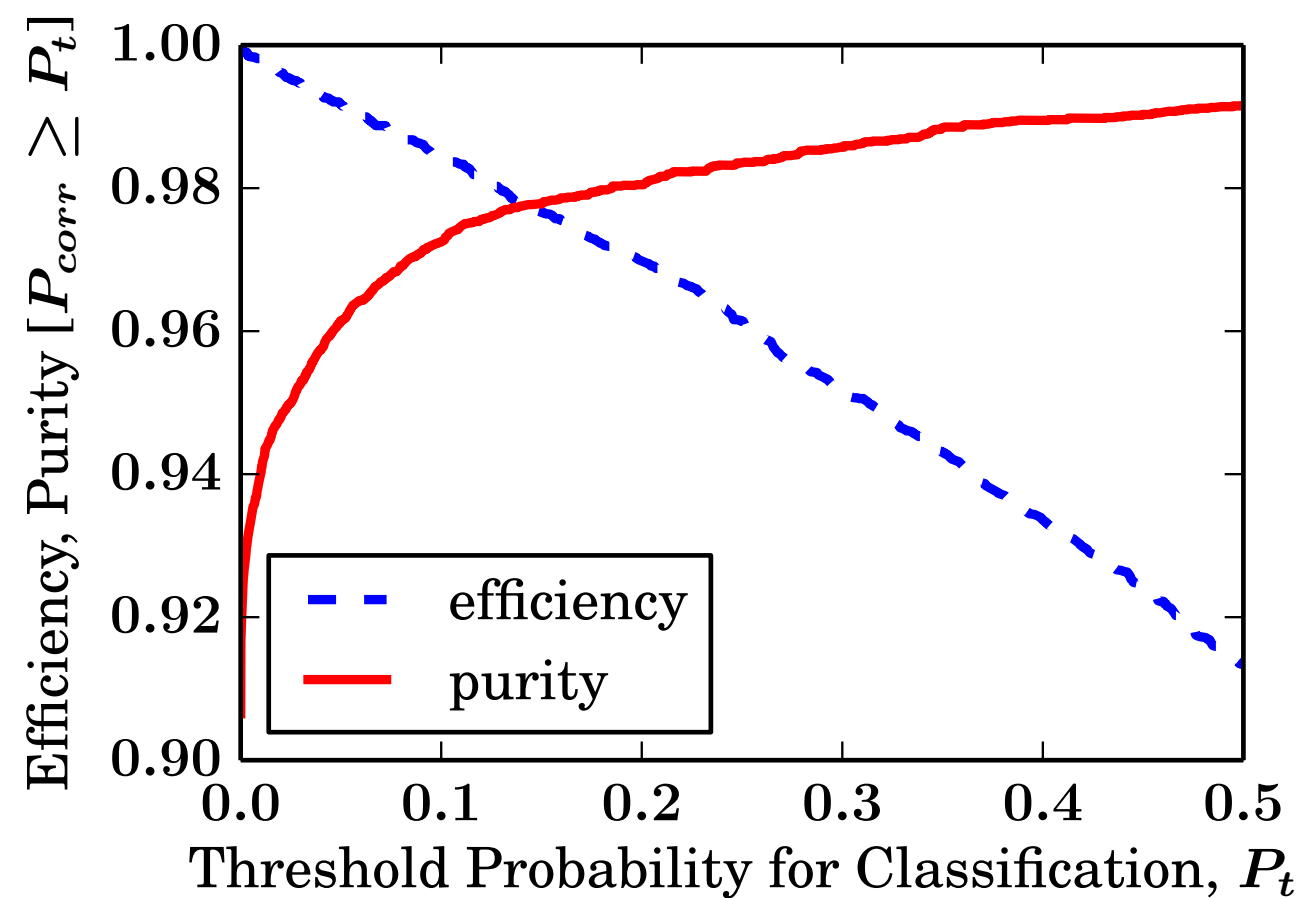
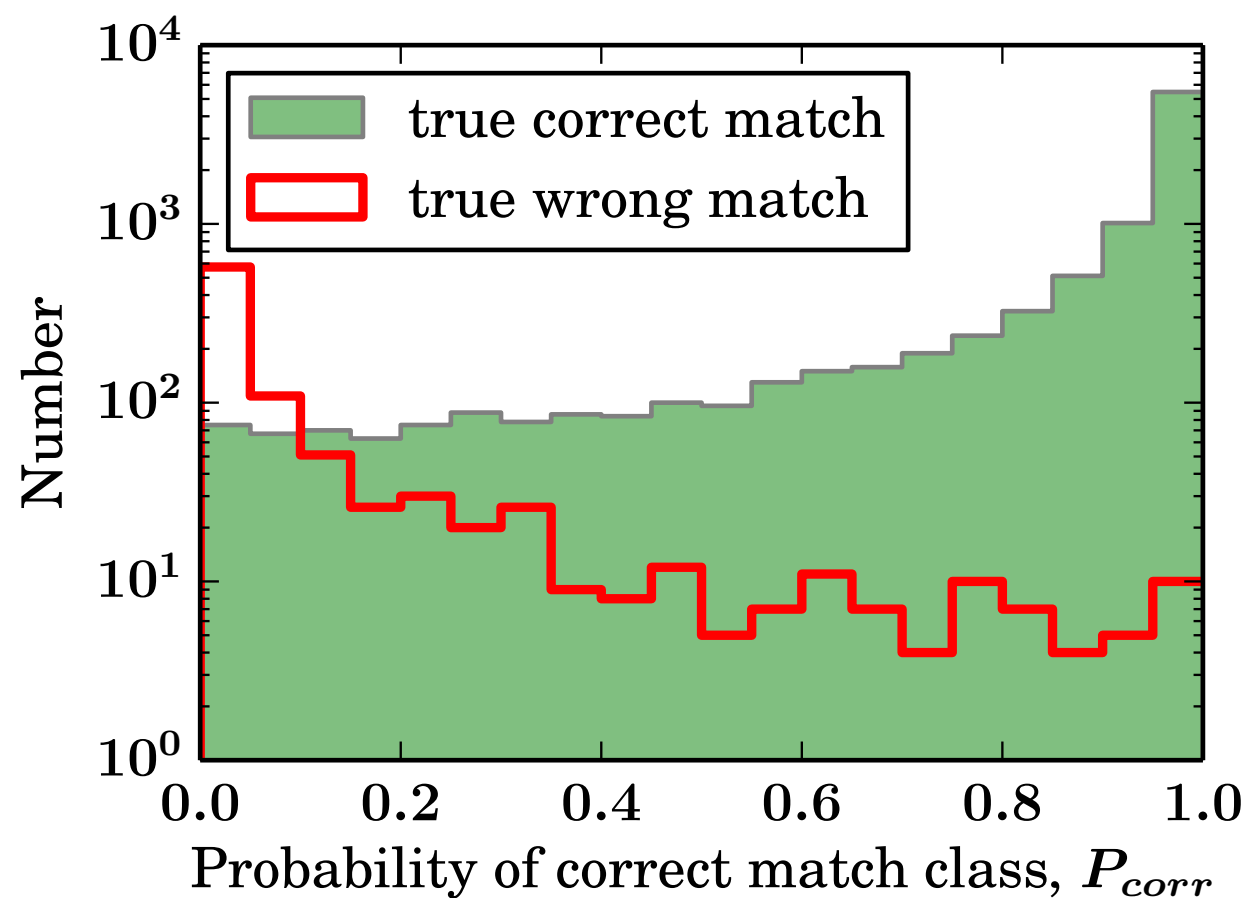
Host Galaxy Matching

(Gupta et al. 2016)

- Host galaxy matching critical for galaxy follow-up
- Inaccurate matching leads to systematic biases
- New methods reach 98% purity (old - 92%)



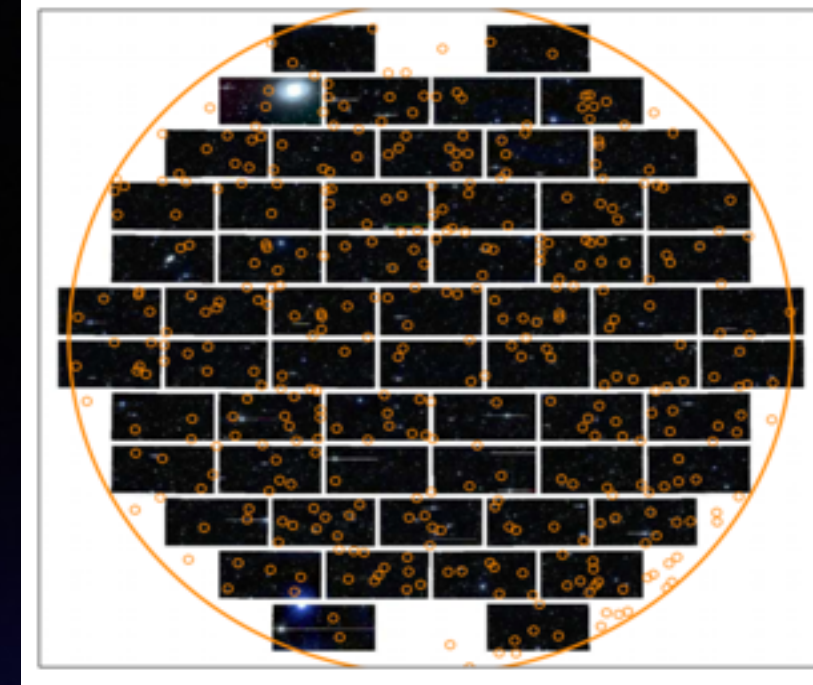
Preliminary:



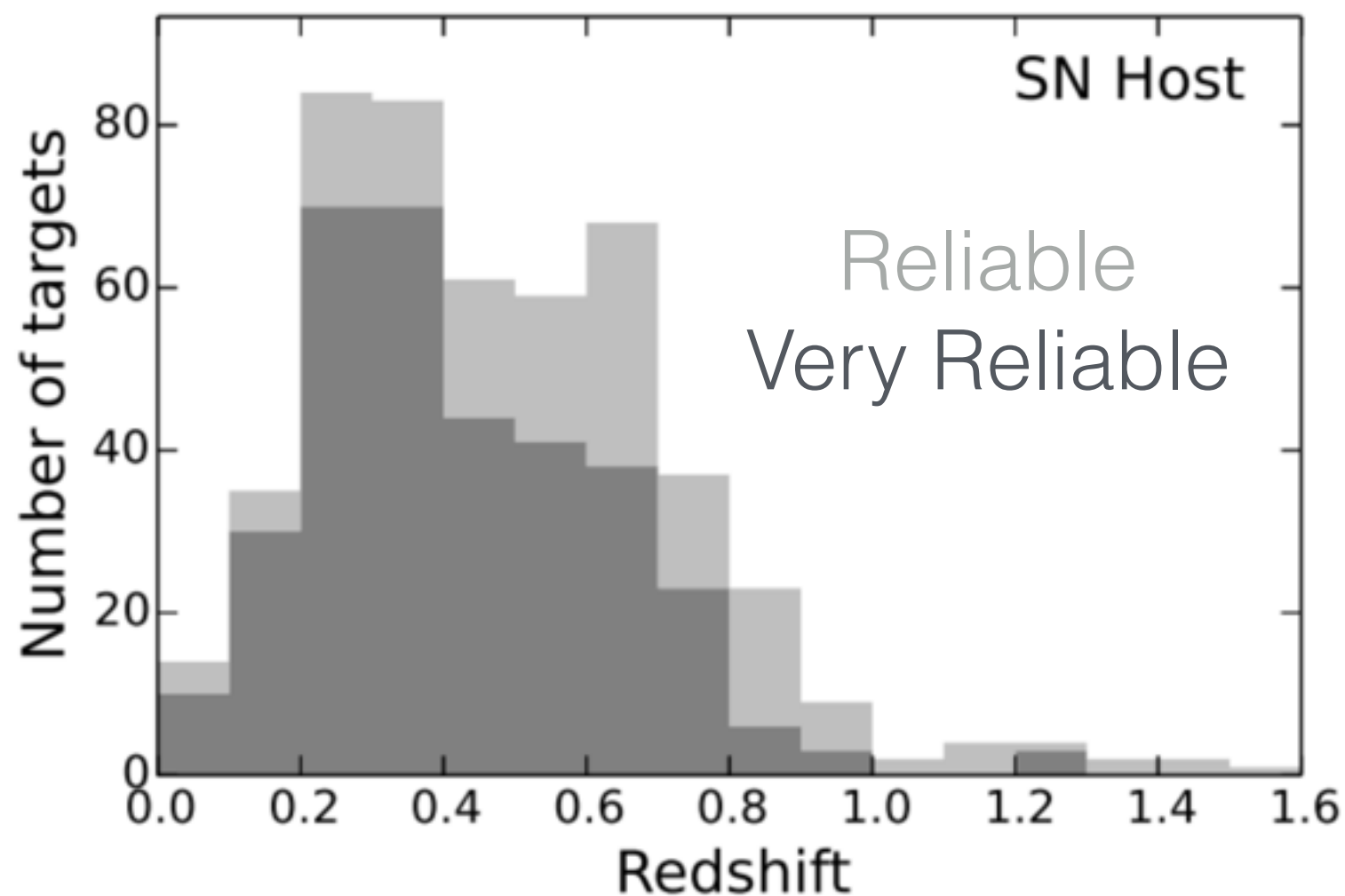
Host Galaxy Follow-up

(Yuan et al 2015)

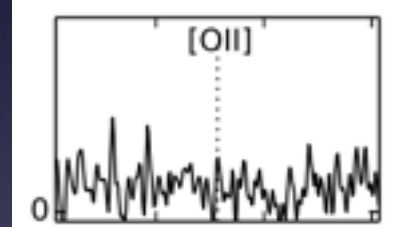
- AAT field-of-view same as DECam field-of-view
- 6000 redshifts measured over AAT-OzDES follow-up
- Improved efficiency with stacking



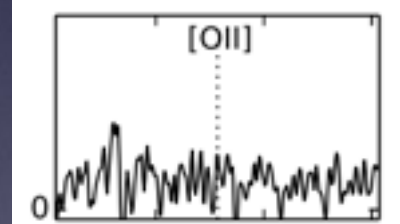
AAT FOV on DECam FOV



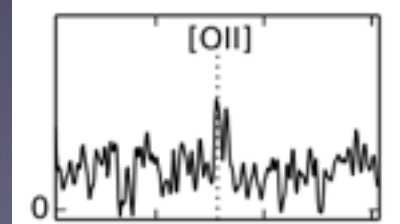
Exp=7200 s



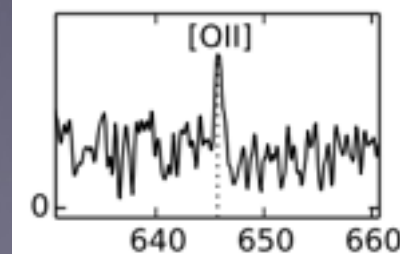
Exp=14400 s



Exp=32400 s



Exp=51600 s



SN Analysis Basics

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Photometry is critical because it gives the measurements of the light curve itself.

The most difficult step in SN photometry is how to make the galaxy templates and do image subtraction

- Two main approaches:
 - Stacking -- convolution -- subtraction
 - Scene modeling

Image convolution and subtraction

The crux of the difference imaging problem is to find a convolution kernel K that matches the PSFs of two astronomical images, I (referred to as the image) and T (referred to as the template). These images in general are taken under different conditions, including atmospheric transparency, atmospheric seeing, or exposure times. One may even difference data taken from different sites and equipment entirely. However, this technique does **not** work well for differencing data taken in different filters - to the extent that instrumental response as a function of wavelength is different on different equipment, differencing data taken from different sites does require some care.

Mathematically, the equation you want to solve is the minimization of the function

$$\sum ([T \otimes K](x, y) - I(x, y))^2$$

by solving for the kernel K . If K can be decomposed onto basis functions, then this is a linear least-squares problem, and can be solved uniquely by matrix inversion. In this method, the kernel is decomposed into basis functions

$$K(u, v) = \sum_n A_n K_n(u, v)$$

$$K_n(u, v) = e^{-(u^2+v^2)/2\sigma_k^2} u^i v^j.$$

By default in **HOTPANTS**, $n = 3$ and

$$\sigma_{k1} = 0.7 \text{ pixels; } i + j \leq 6$$

$$\sigma_{k2} = 1.5 \text{ pixels; } i + j \leq 4$$

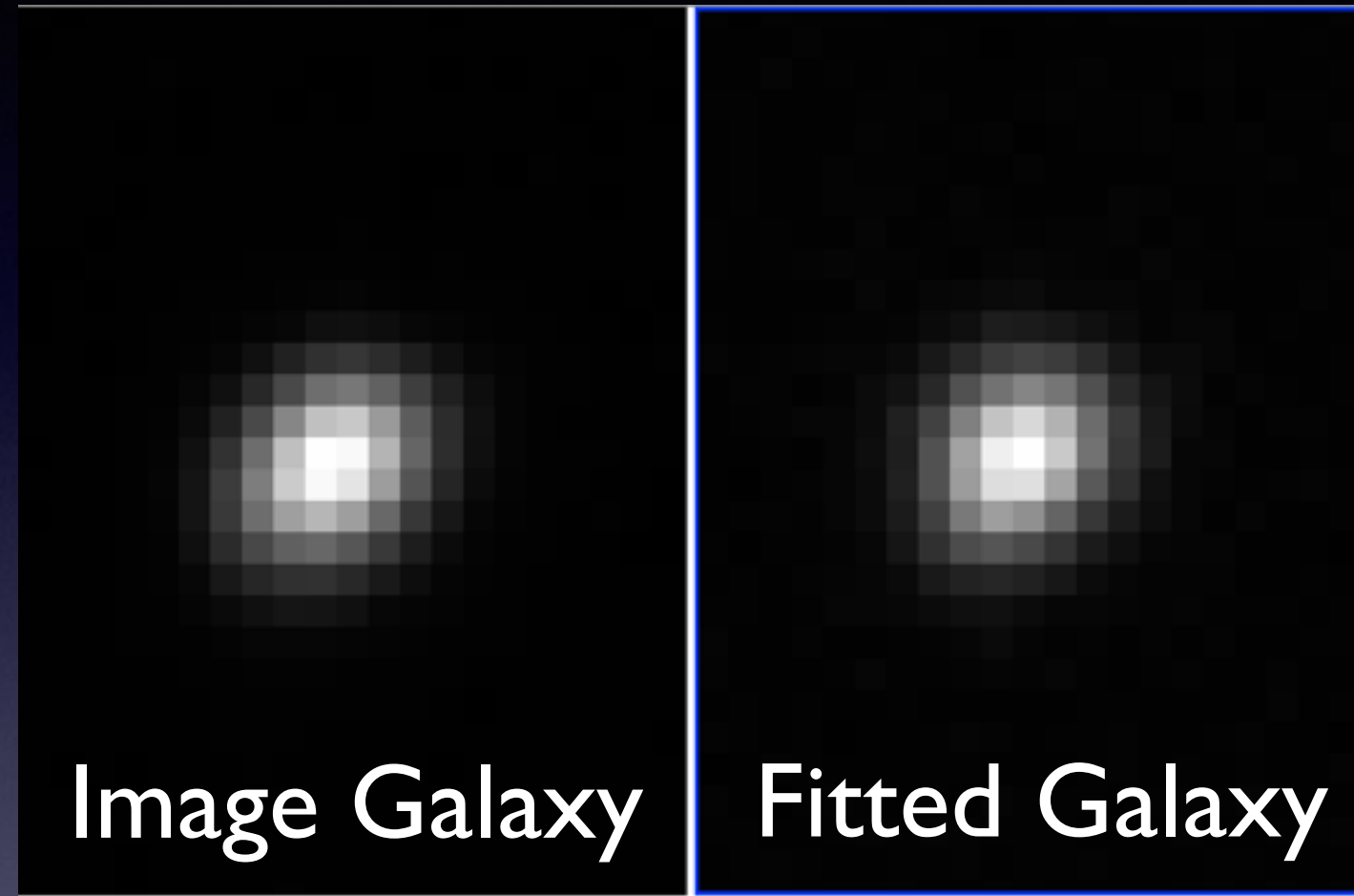
$$\sigma_{k3} = 3.0 \text{ pixels; } i + j \leq 2$$

Have to build a template from multiple images first to make T

The second approach is to do scene modeling

Forward modeling of a galaxy on a pixel-by-pixel grid

- Does a $n_pix \times n_pix$ + n_image fit over SN brightness and galaxy intensity



$$M(x, y) = sky(x, y) + S \left(\sum_{stars} I_{star} PSF(x - x_{star}, y - y_{star}) + I_{SN} PSF(x - x_{SN}, y - y_{SN}) + \sum_{x_g, y_g} G(x_g, y_g) PSF(x - x_g, y - y_g) \right)$$

Holtzman
2008

$$\chi^2 = \sum_{xy} \frac{(O(x, y) - M(x, y))^2}{(M(x, y)/G + (\frac{\sigma_{sn}^2}{G^2}))}$$

O=Image

I=Intensity, G=Galaxy, M=Model

Photometry

Two independent pipelines

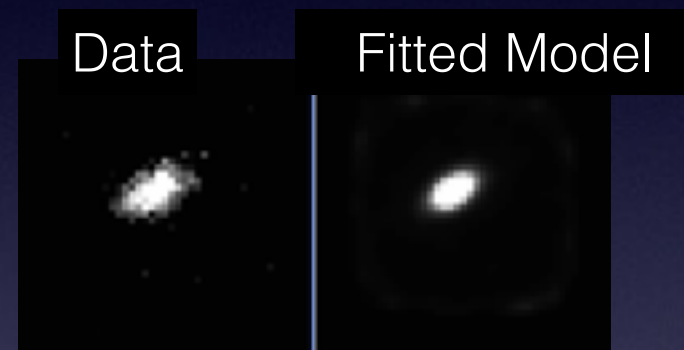
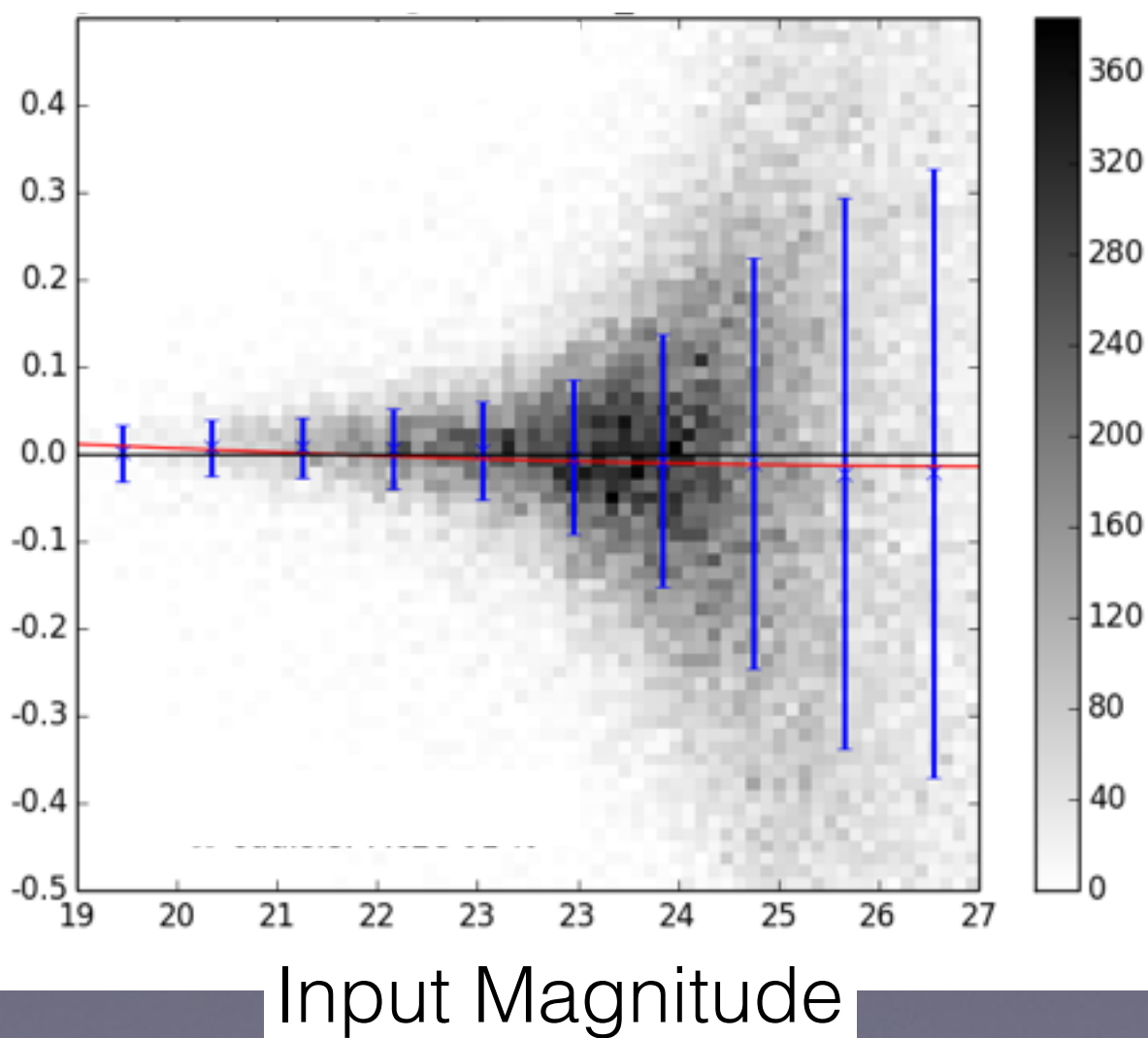
+Image Subtraction

+Scene Modeling

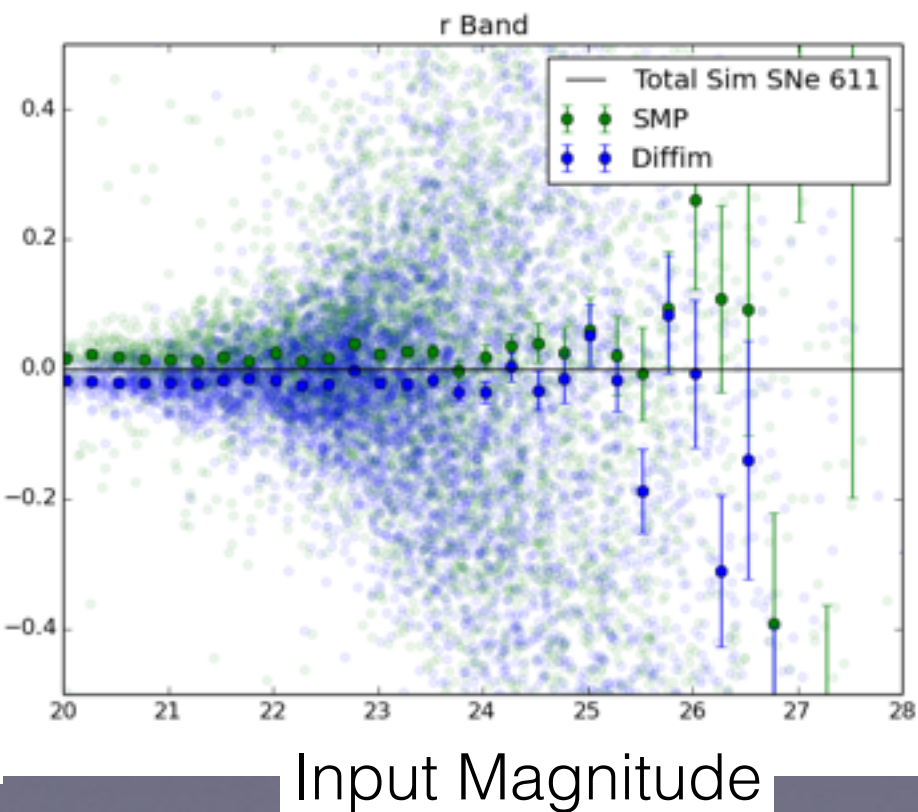
-Sub 1% biases, more scatter with increasing galaxy brightness

-Forward modeling of galaxies by solving for temporally constant galaxy and fluctuating SN flux

Recovered - Input Magnitude



Recovered - Input Magnitude

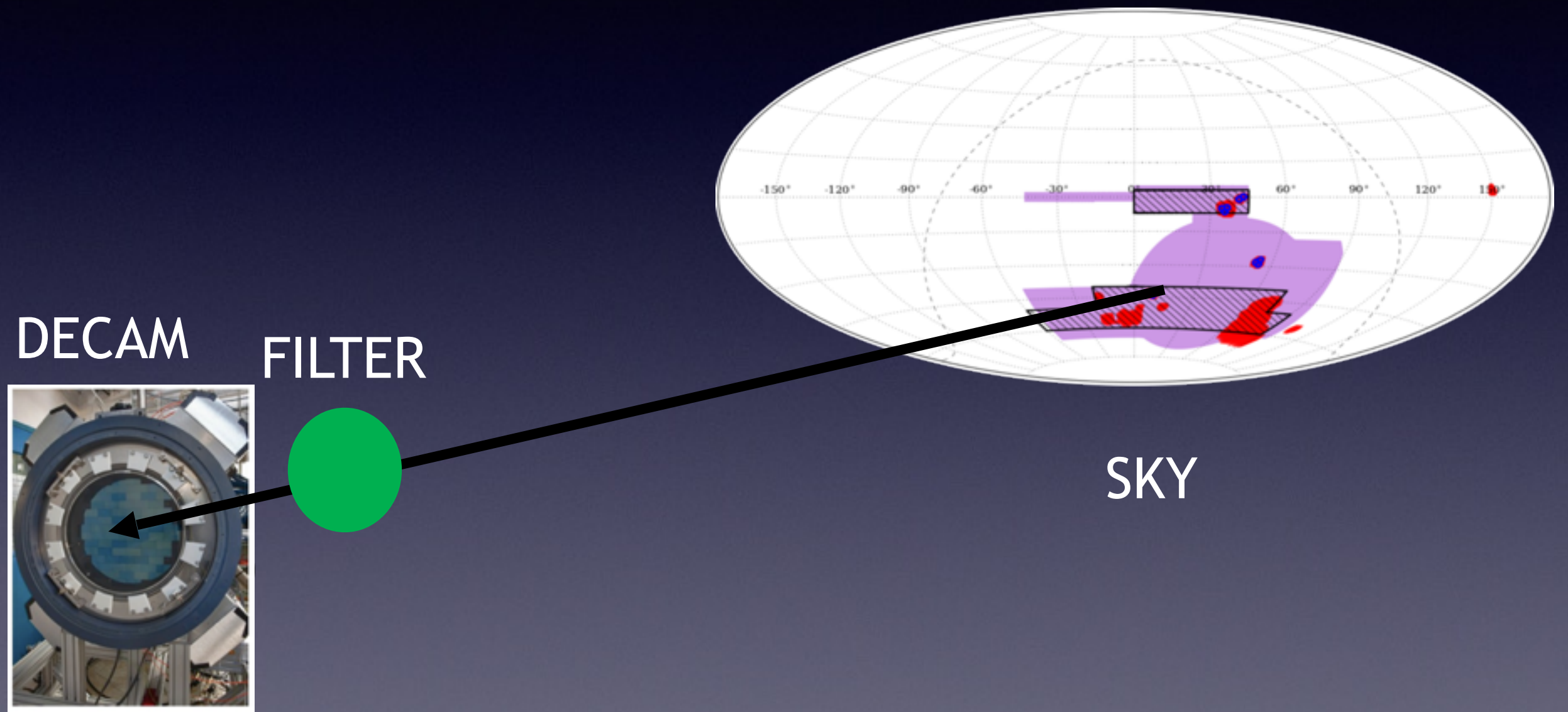


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Calibration is critical because the light of the SN will peak in different filters depending on its redshift. If filters aren't calibrated against each other, can introduce a cosmological bias.

The Path to Calibration.....



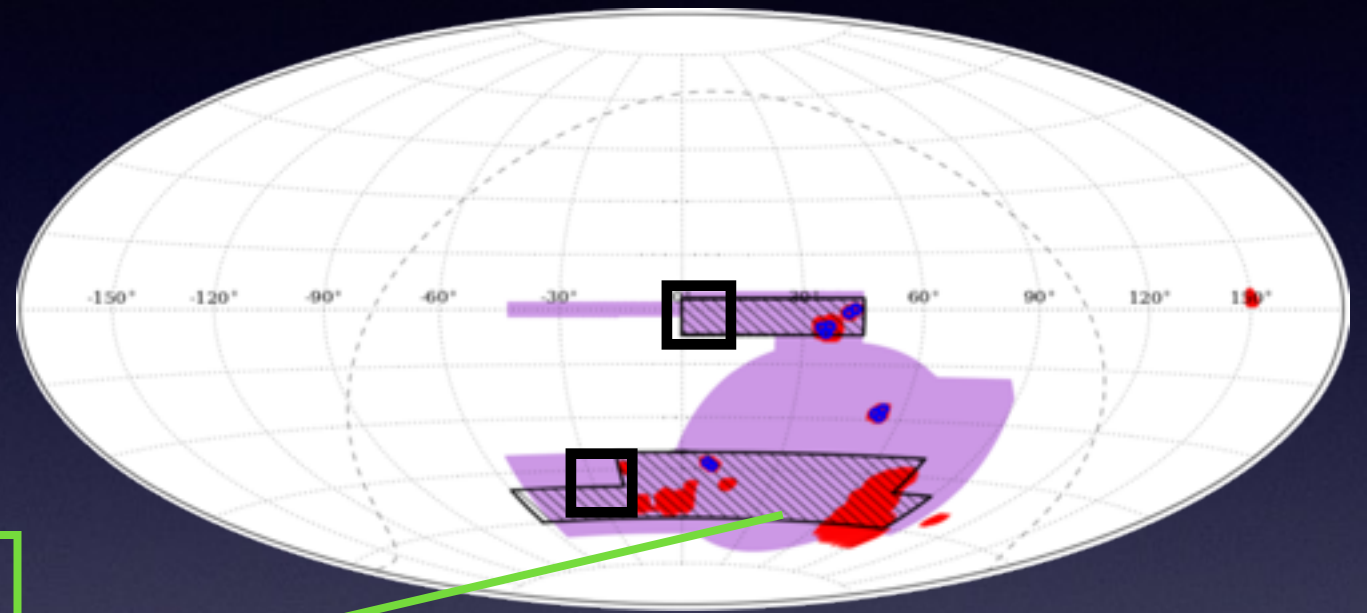
Courtesy of our own James Lasker

Possibilities for error abound!

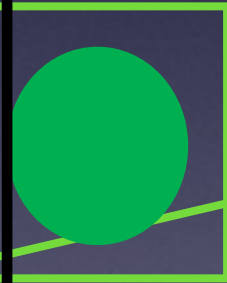
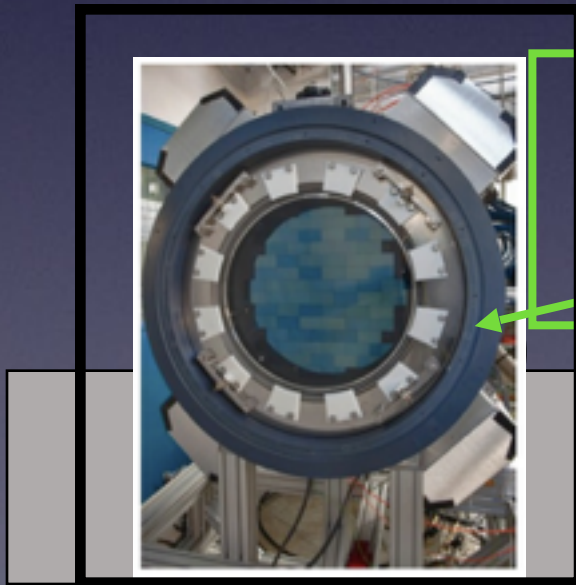
Temporal
+ spatial
varying
camera
efficiency

Atmospheric
Fluctuations

Imprecise
Filter
Measurements



Difference across
sky



Calibration:

- Dominant systematic in past analyses
- Joint effort with Wide Area Survey

Absolute
Calibration

Observed and
synthetic photometry
of Calspec standards

Measurement
of DECam
transmission
function

Field-to-
Field
Calibration

Measure zeropoint
repeatability and SLR
between SN fields

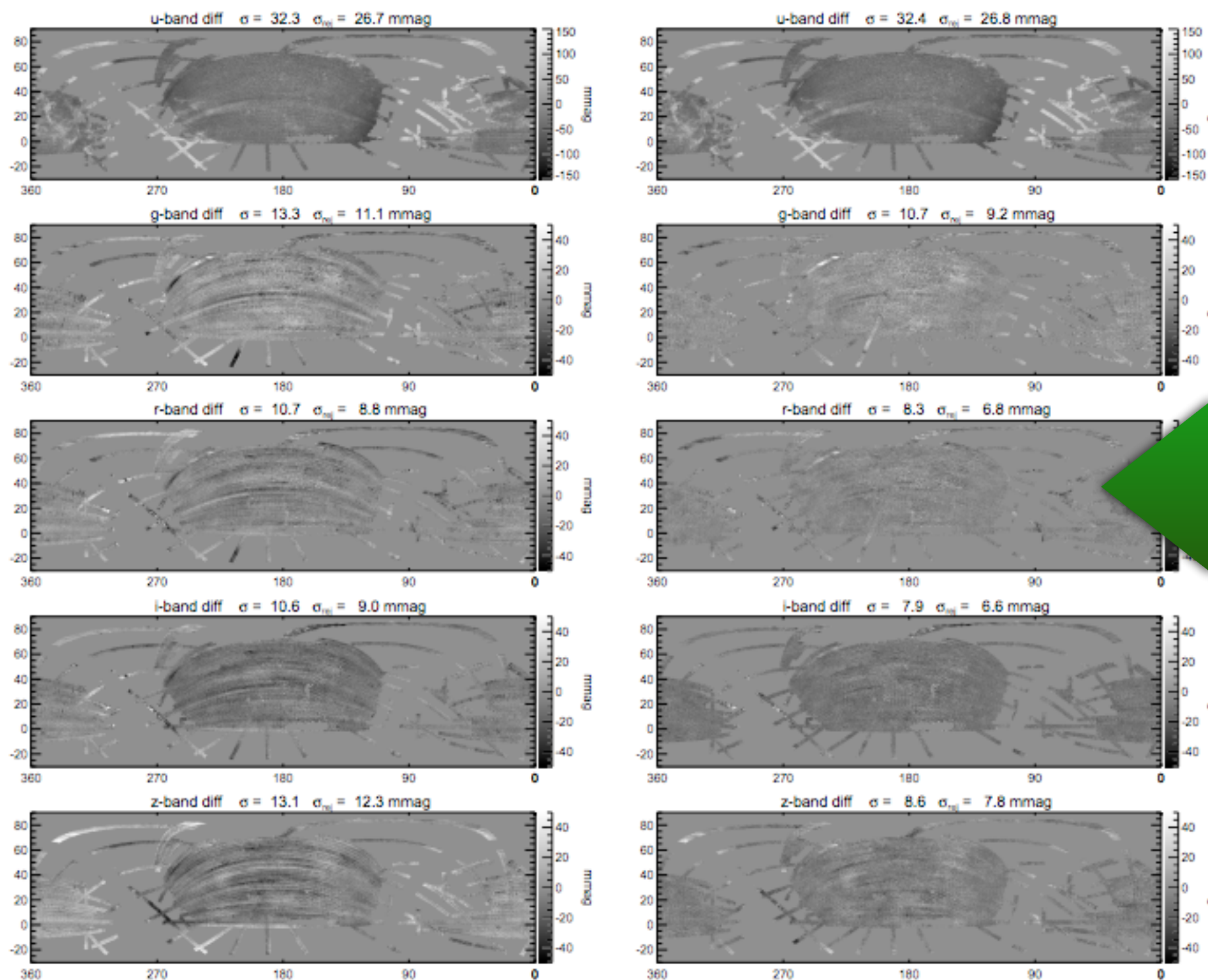
Use aTmCam to
correct for effects of
water and aerosols
(Ting 2016 - arxiv)

Instrumental
Calibration

Photometry of SN
fields

Within-field Calibration

To improve systematic uncertainty, the key is to improve calibration between surveys



Schlafly, Finkbeiner et al. did PS1 Ubercal, relative calibration across sky <5 mmag, <3 mmag for MD fields

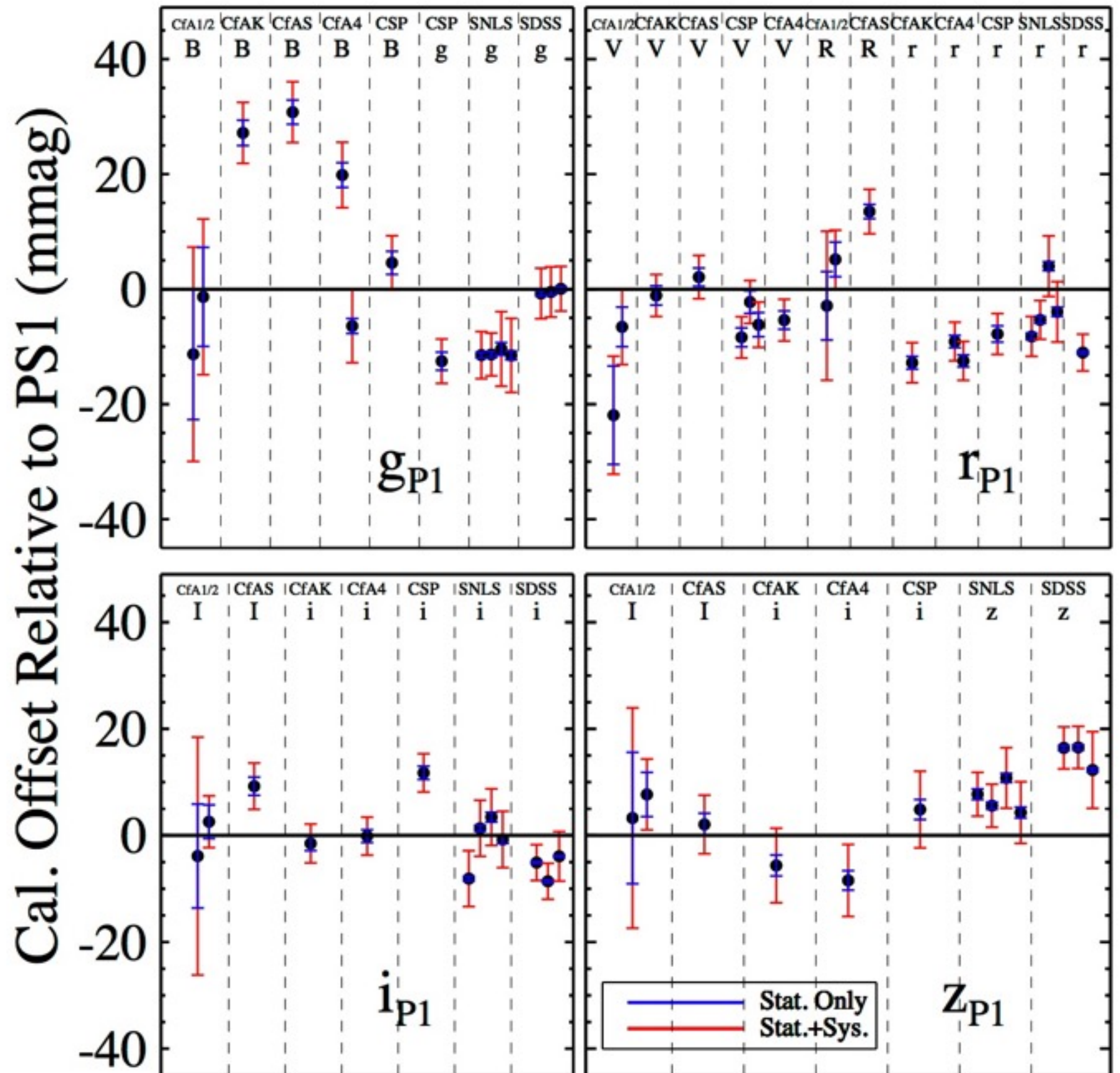
Compared PSI to SDSS, found SDSS issues

Scolnic et al. 2015 cross-calibrates all supernova samples!

FIG. 1.— The mean difference (PS1 minus SDSS) in 15 arcminute fields in the southern portion of the PS1 field.

FIG. 2.— Same as Fig. 1, but after recalibration. The calibration is indicated by the color scale on the right of each panel.

Doing this for
all available
public data,
measure an
offset for
each filter for
each system.



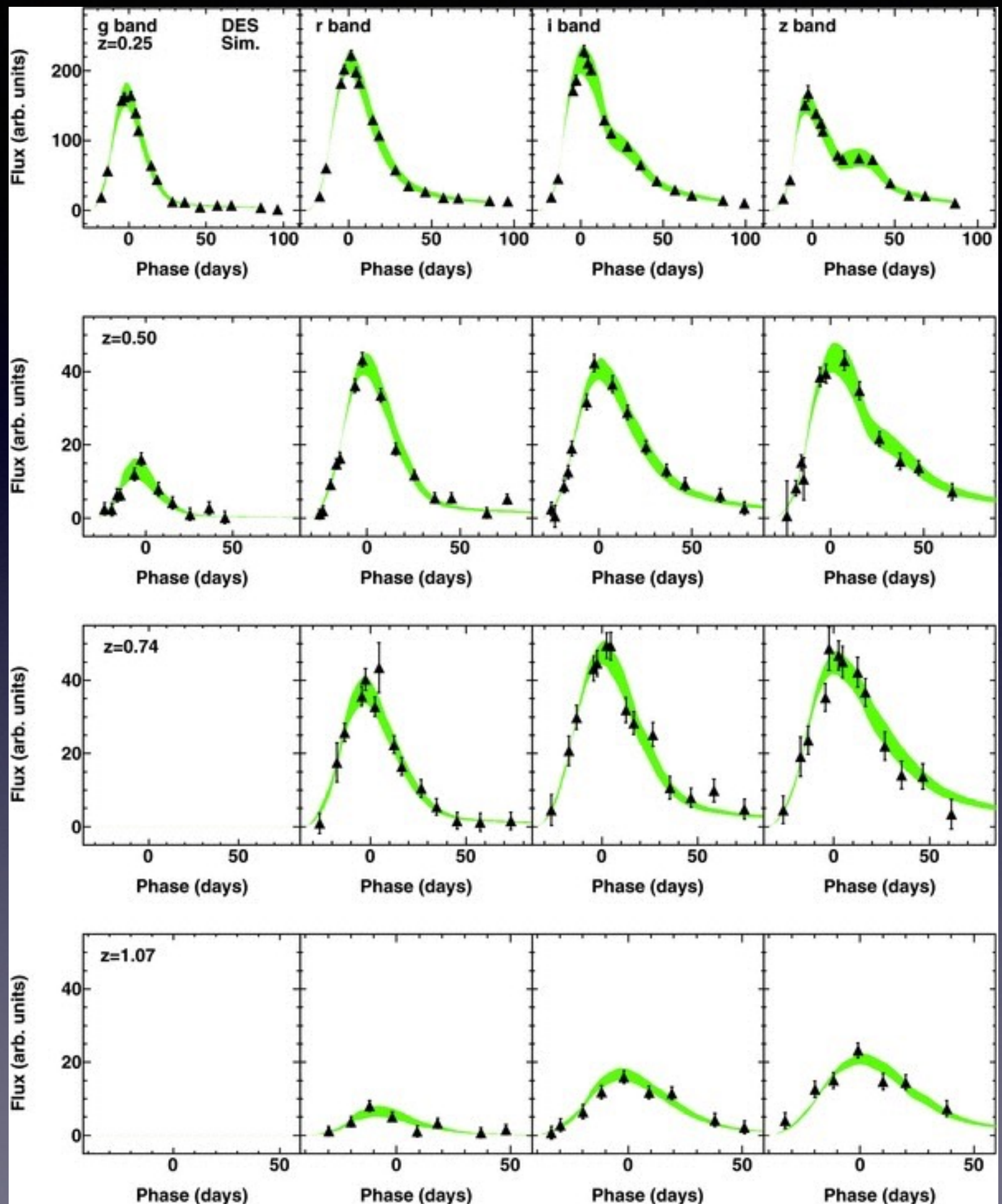
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Light-curve fitting is what translates your light curve into fit parameters that can be converted into a distance.

For each light curve
for all bands,
measure a light
curve amplitude,
color (diff between
bands) and width

Distance = $mb + ax1 - b * c$
 mb = amplitude
 $x1$ = width
 c = color
 a, b are coefficients

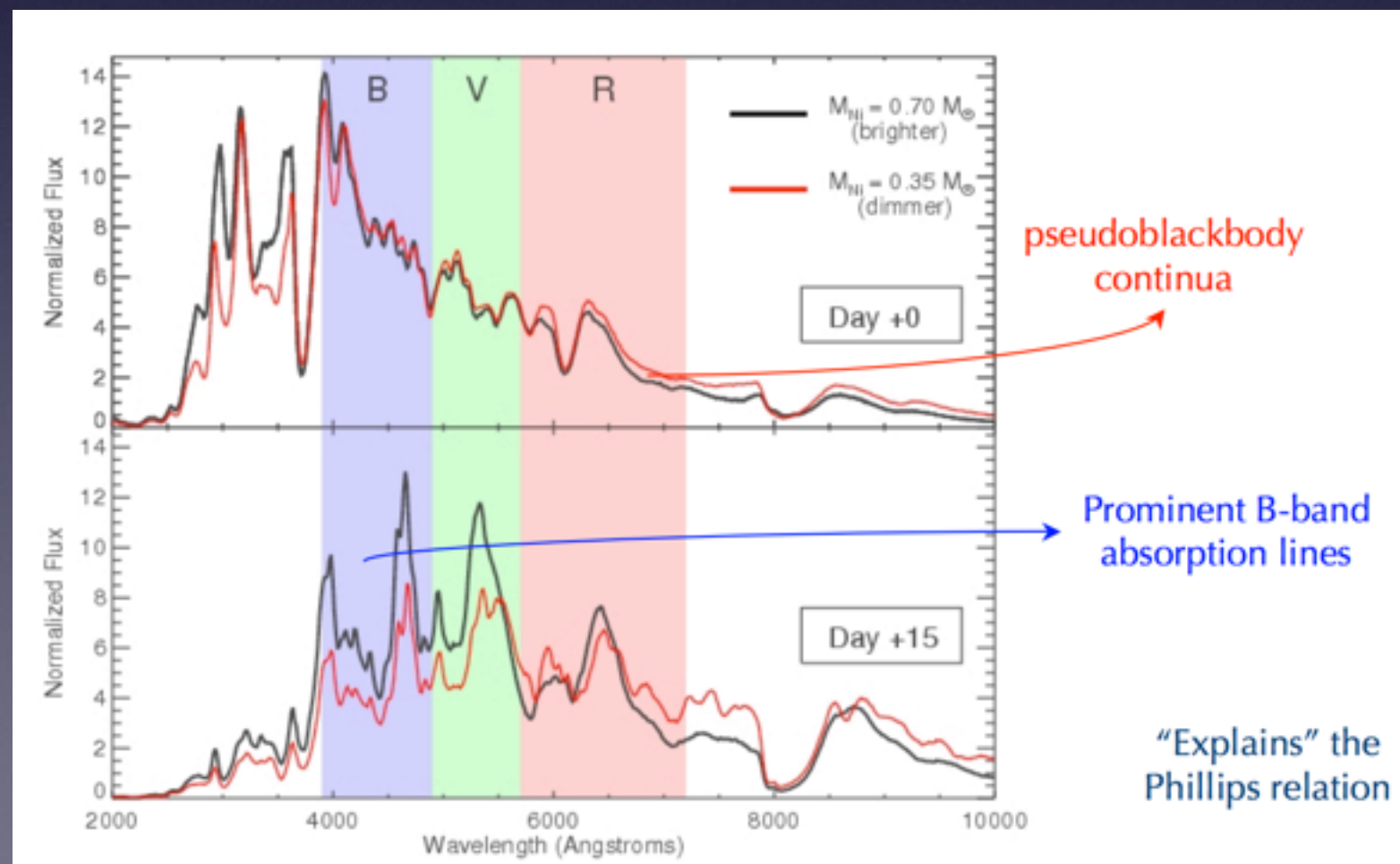
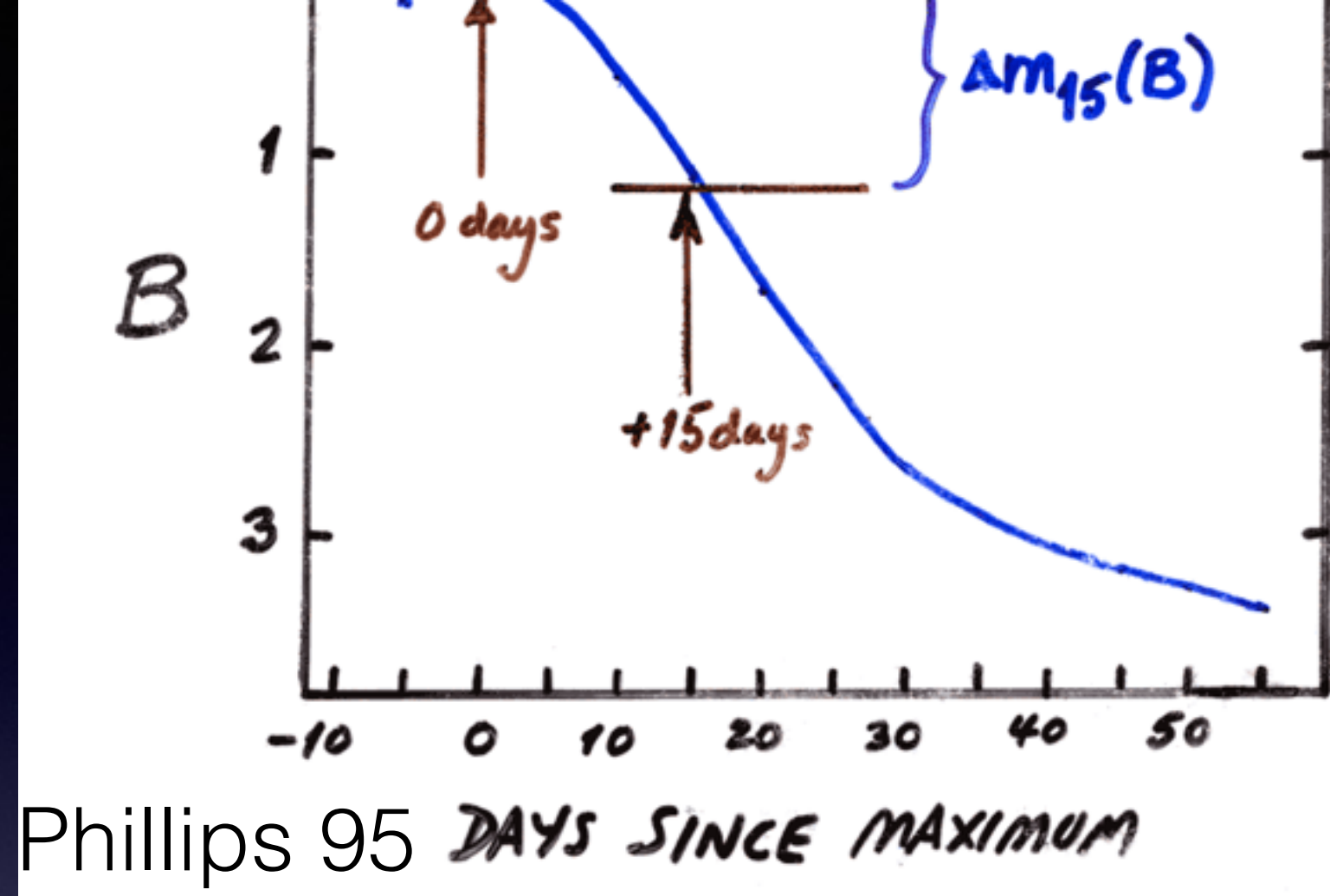


Standardization works because of Phillips relation

Following maximum light, the SN colors are increasingly governed by the blanketing of numerous Fe II and Co II lines that particularly affect the B band

Because dimmer SNe Ia are cooler, they experience an earlier onset of Fe III to Fe II recombination, resulting in more rapid evolution of the SN colors to the red

The faster B-band decline rate of dimmer SNe Ia thus reflects their faster ionization evolution

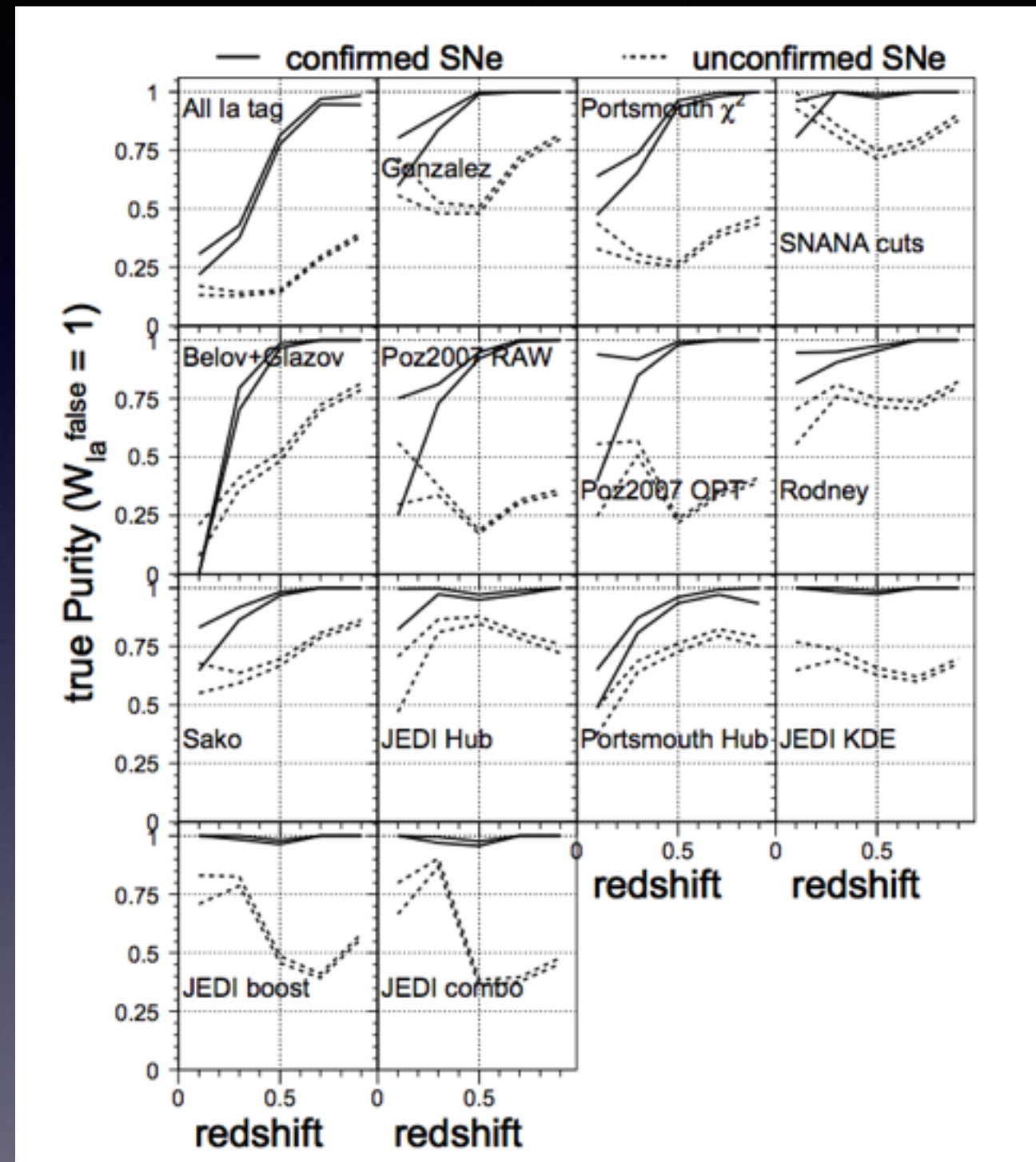
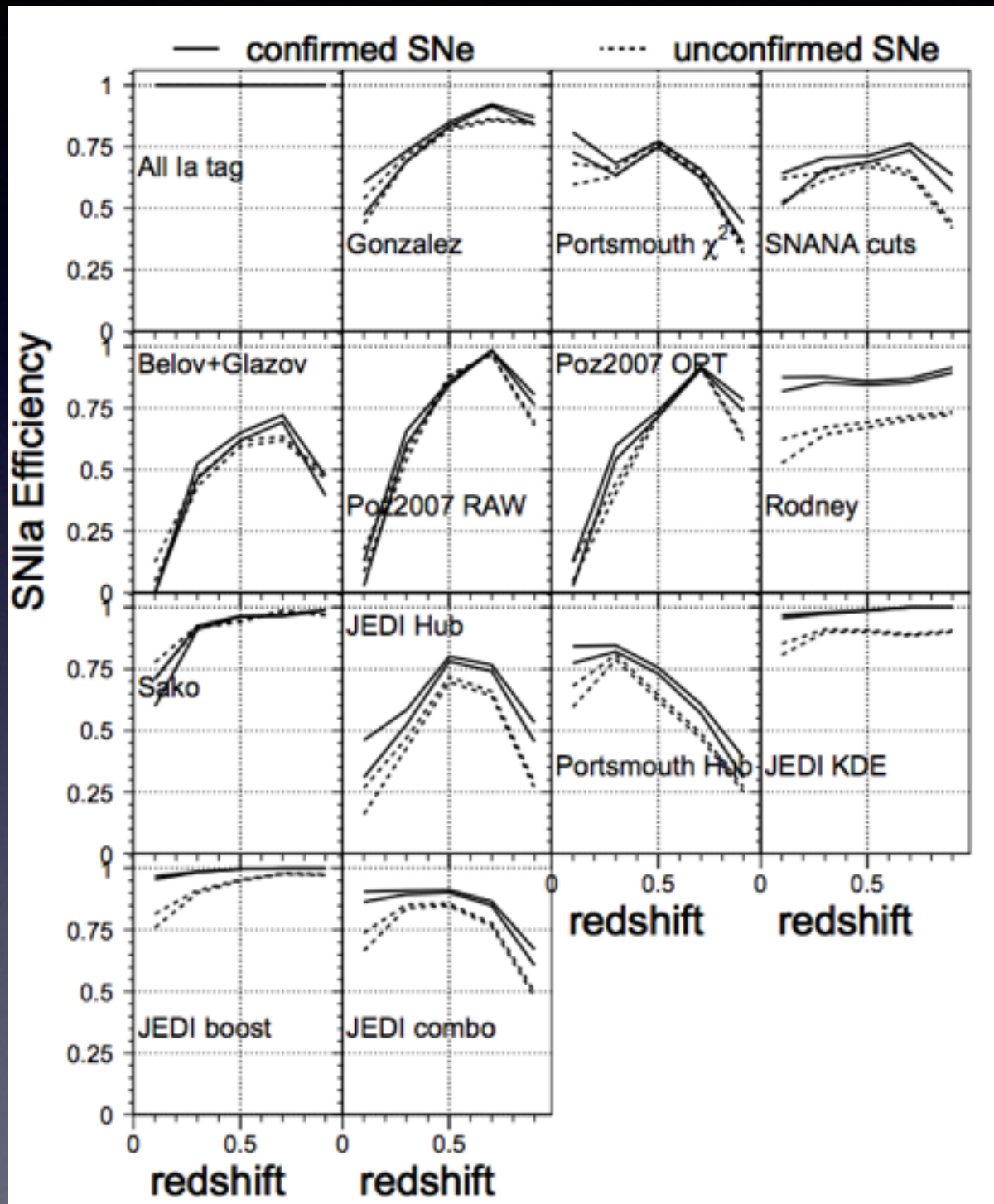


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With DES, can't spectroscopically confirm each SN like in past surveys. But only SNIa are useful for cosmology analysis. So we need to photometrically classify SN.

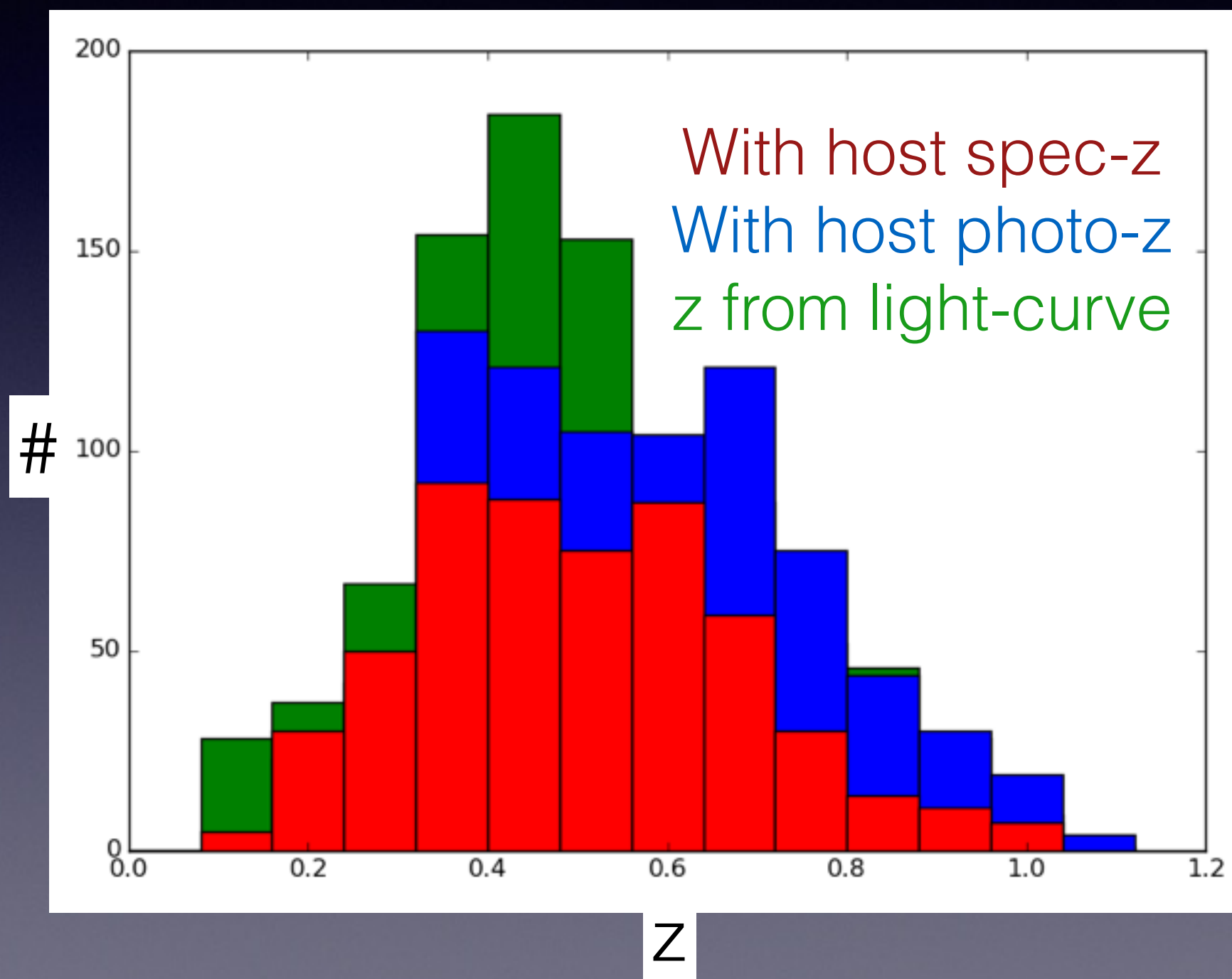
There are multiple techniques that use light curves to photometrically classify (Kessler Classification Challenge)



and some that use host galaxy properties (Jones 16)

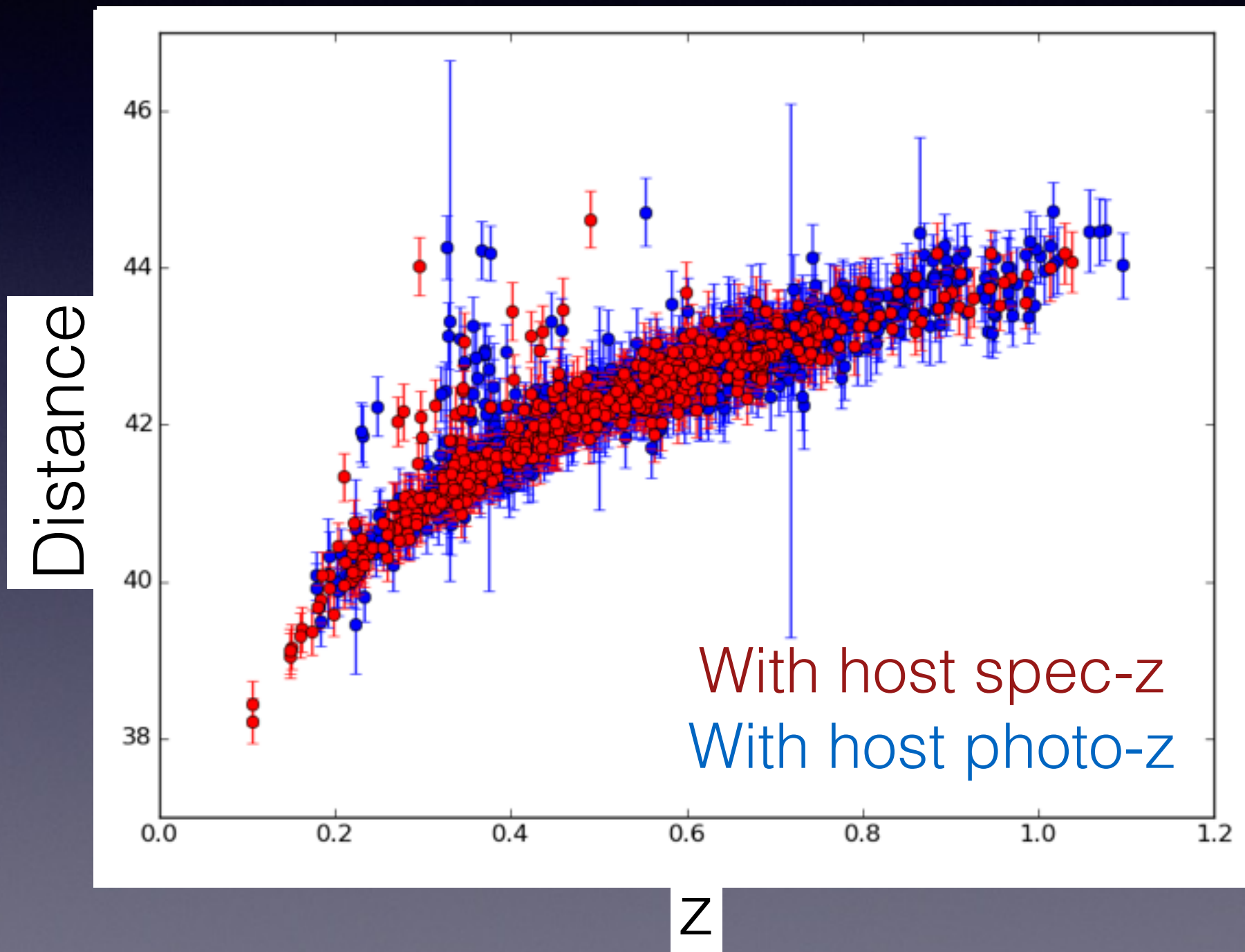
Photometric Classification

- 900 (Y1+Y2) likely SNeIa for cosmology, pass rigorous cuts
- > 800 have good host photo-z
- > 530 have host spec-z

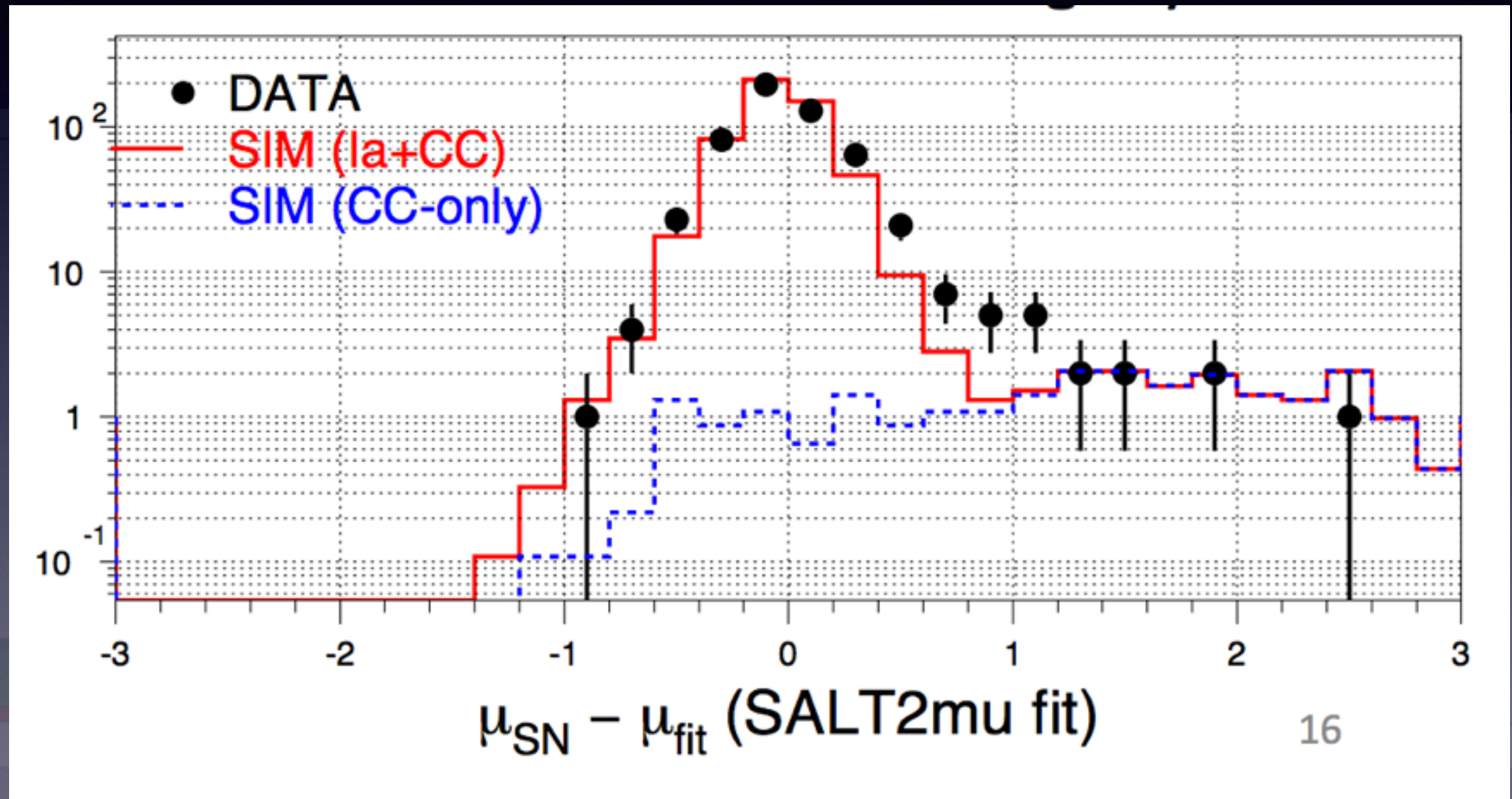


Hard part is that the redshift distributions are different cause only spectroscopically classify lower-z

This is what a Hubble diagram with photometrically classified SNe looks like. Those outliers are likely not SNIa. But what to do about this?



One idea is that we need to understand the shape of the outlier distribution by simulating samples with SNIa and CC SNe



SN Analysis Basics

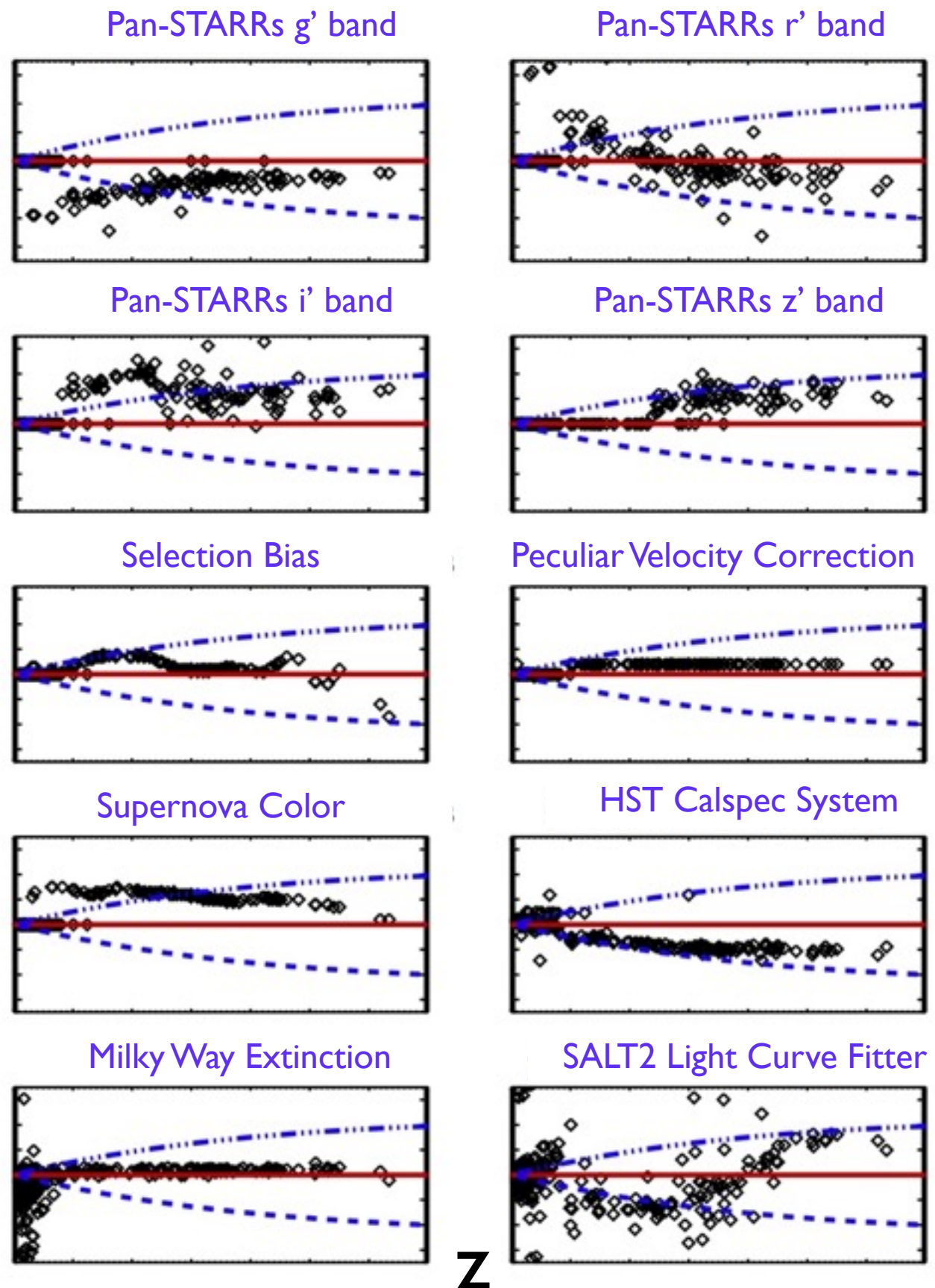
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The error on cosmology measurements due to systematics are of equal size to statistical uncertainty.

To measure w to 10%, we need careful accounting of systematics

Here we show Hubble diagram differences when we change our biggest systematics by 1σ

$\Delta m - M$ (mag)



w+0.05

w-0.05

w+0.05

w-0.05

w+0.05

w-0.05

w+0.05

w-0.05

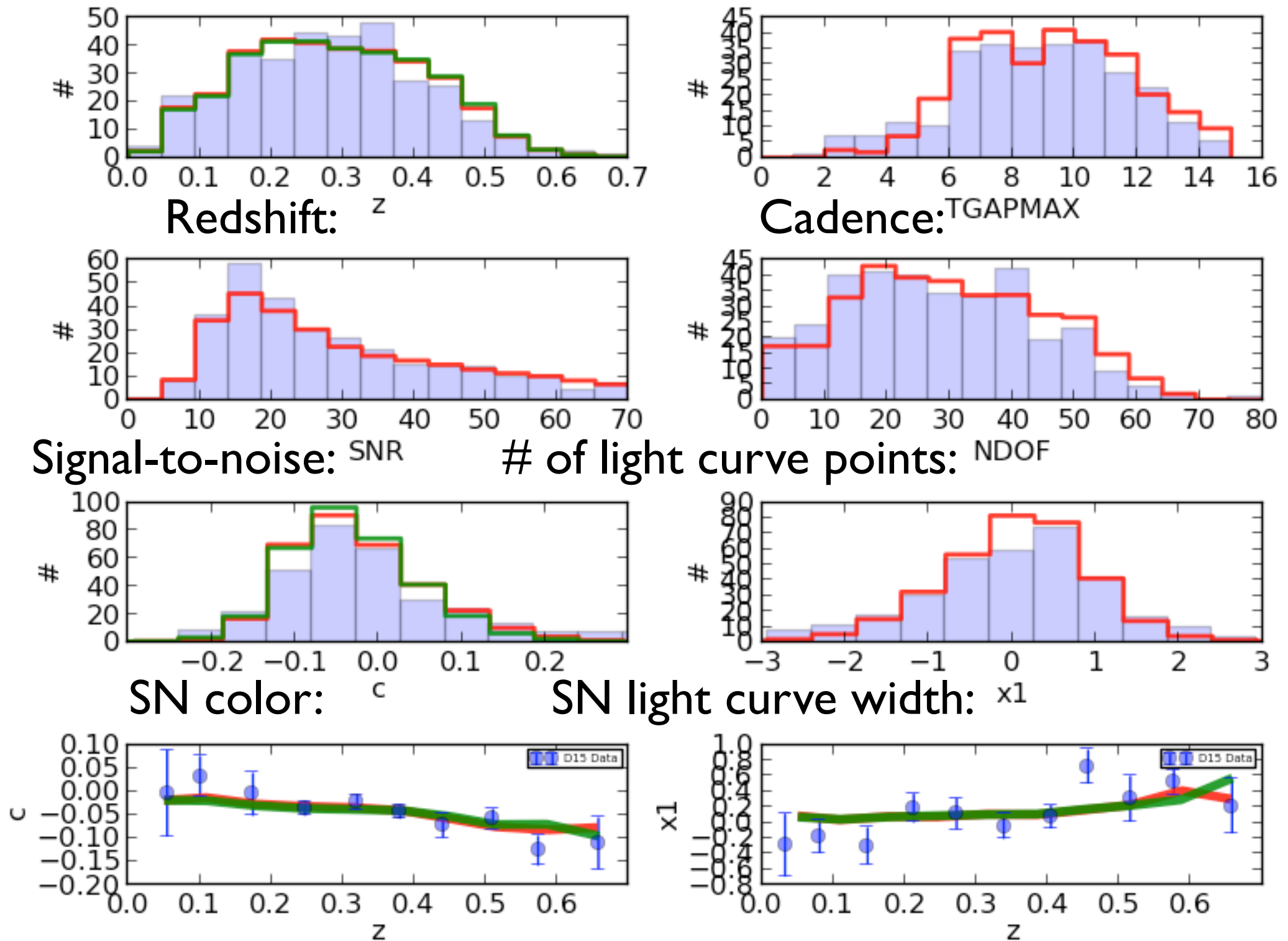
w+0.05

w-0.05

Systematic uncertainties are of similar size to statistical uncertainties. Propagate systematic uncertainties to covariance matrix.

Based on Scolnic et al 14b

To properly analyze survey, critical to simulate survey very accurately.

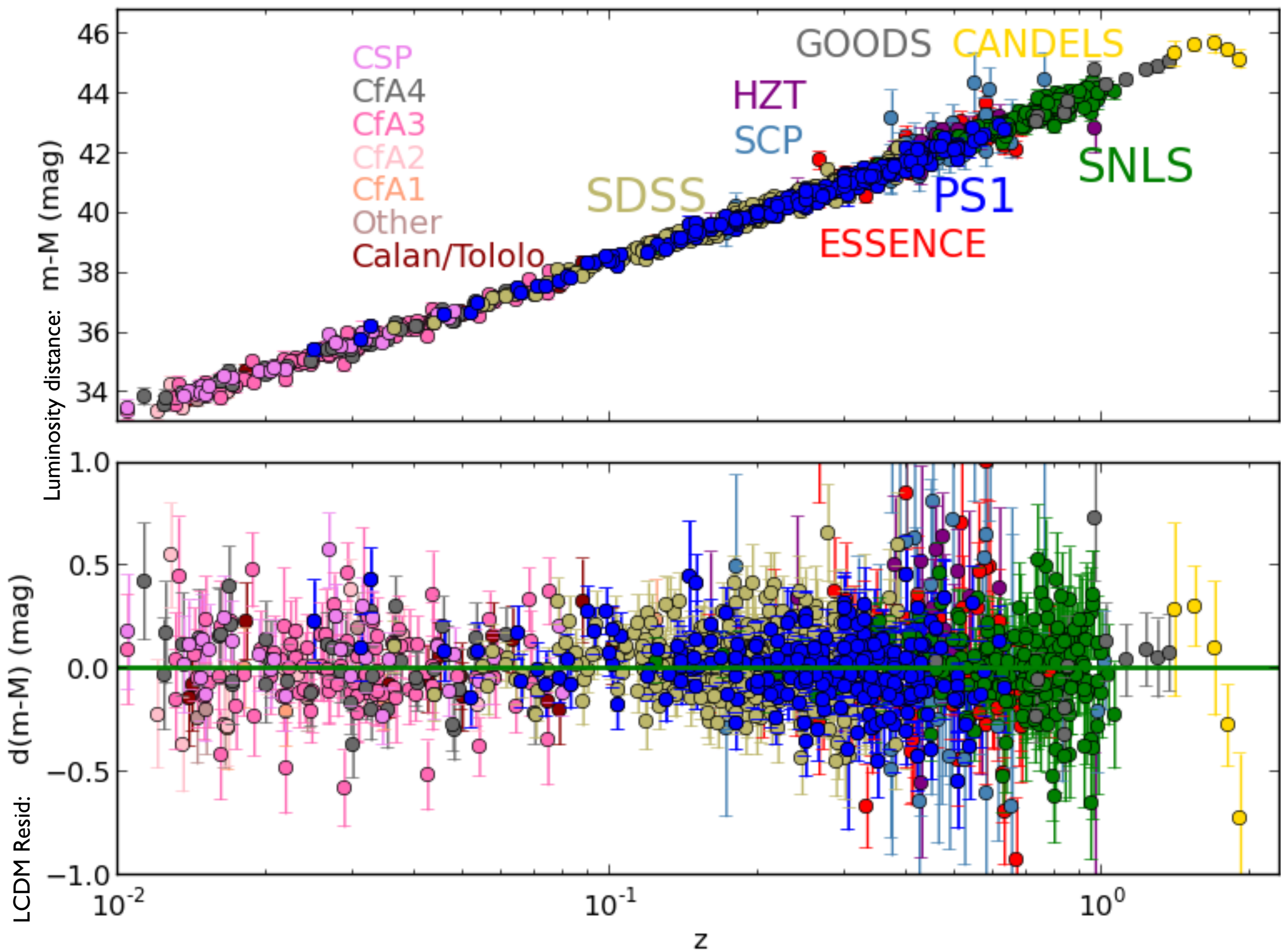


Using SNANA (Kessler 09)

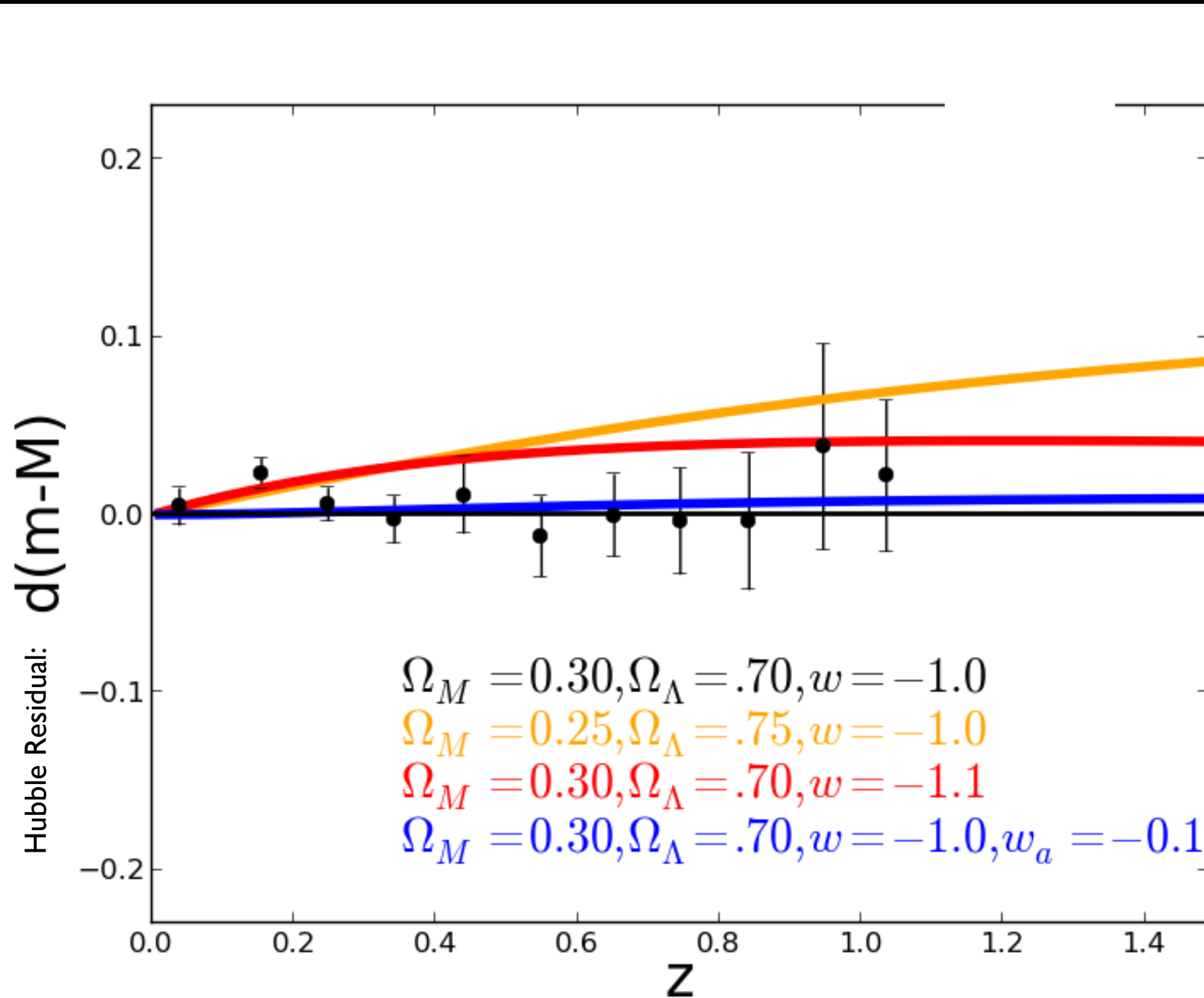
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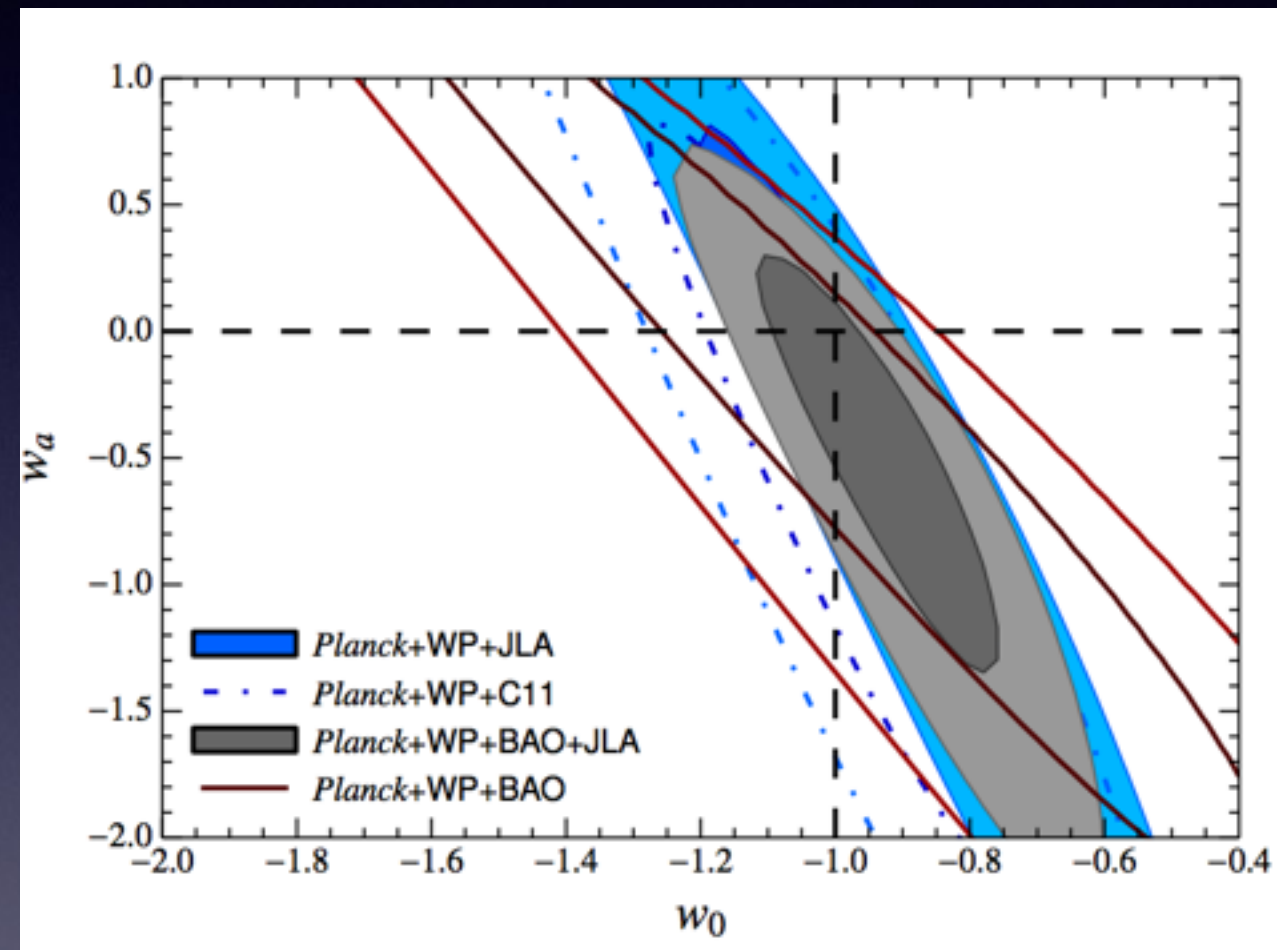
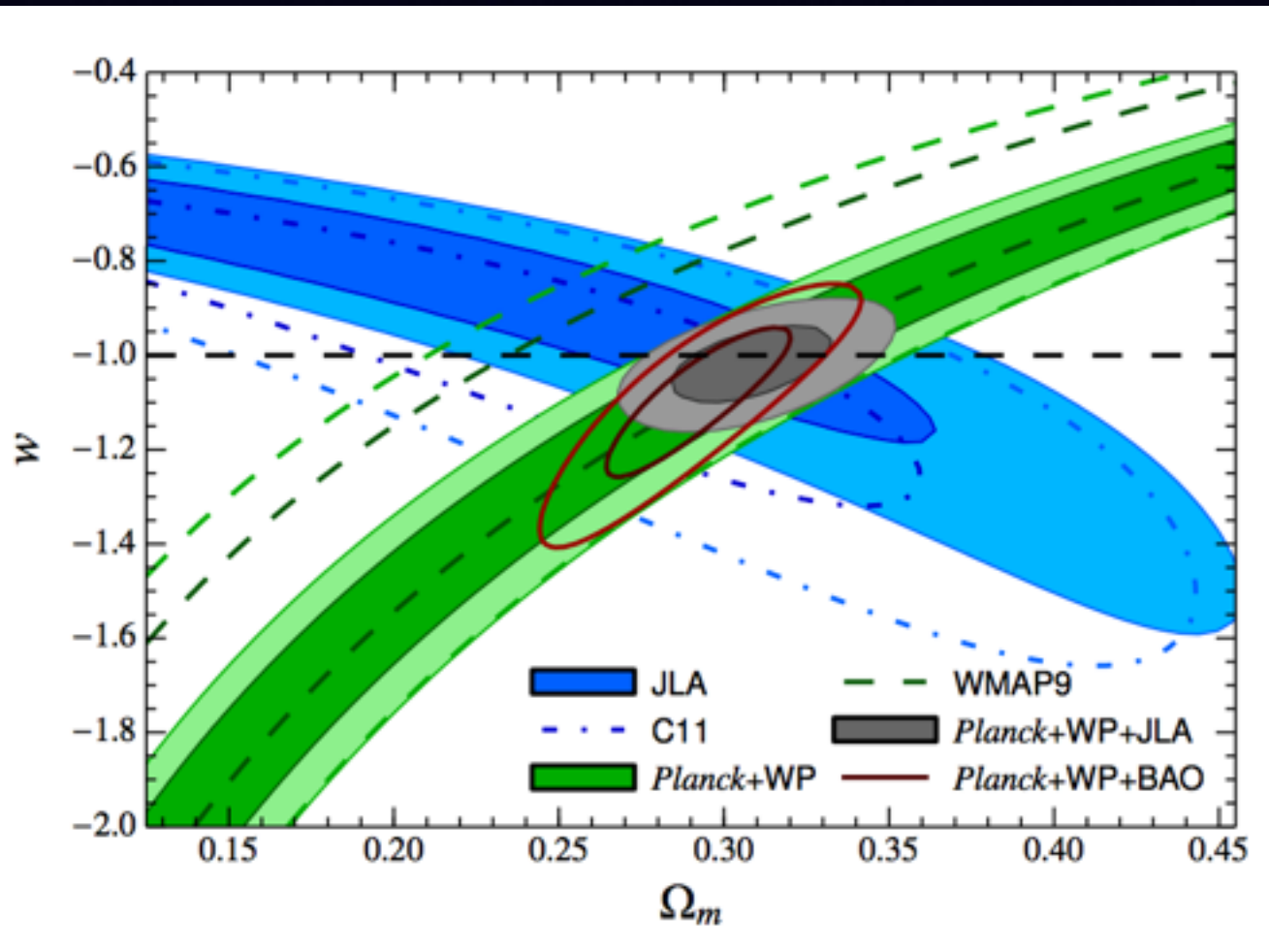
Measuring cosmology is why we are
doing this survey in the first place.



Ultimately, you want to measure cosmology.



The parameters we typically measure are Ω_m , w , w_a



The constraints on w_a are still really large, and that's where DES can make its biggest mark.

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